

Ch: 1, 2

Passive elements

	R	L	C
Voltage (v)	Ri	$L \frac{di}{dt}$	$\frac{1}{C} \int_{t_0}^T idt + v(t_0)$
Current (i)	$\frac{v}{R}$	$\frac{1}{L} \int_{t_0}^T v dt + i(t_0)$	$C \frac{dv}{dt}$
Power, $P=vi$	$i^2 R, \frac{v^2}{R}$	$Li \frac{di}{dt}$	$Cv \frac{dv}{dt}$
energy stored	0	$\frac{1}{2} Li^2$	$\frac{1}{2} Cv^2$
AC condition	$v = IR$	$v_L = Ix_L = IwL$	$v_C = Ix_C = \frac{I}{wC}$

"حب اسعد الناس يجعله تبدع وتفعل ما لا تخلي سوق فعلم"
 (محمد فتحي)

ملخصات

- * تأثير L و C يظهر في الفترة الانتقالية سواء في AC أو DC أما R لا يظهر في AC طبعاً.
- * المقاومة لا تخزن الطاقة وإنما تبدها.
- * الملف يخزن الطاقة في شكل مغناطيس.
- * الائتمان يخزن الطاقة في شكل كهربائي.

- * An Inductor does not permit an instantaneous change in its terminal current. الملف لا يسمح بغير لحظي في التيار
- * An capacitor does not permit an instantaneous change in its terminal voltage.
- * An resistance permit an instantaneous change in its terminal voltage and current.

At steady state

- * Inductor appears as a short circuit in relation to constant terminal current.
- * Capacitor appears as open circuit in relation to constant terminal voltage.

Active elements

- Independent current source. مصدر يعطى تيار هيكلا ثابت
- Dependent current source. يعطى تيار قيمته نسبتاً تياراً آخر في الدائرة.

Types of circuits

(1) first order

- * RL - RC circuits [natural - step response] تم دراستهم

(2) second order

RLC circuits

Response

الاستجابة الناتجة عن تغير ما

① natural response.

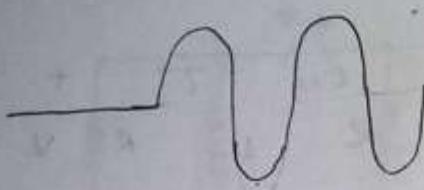
* الدائرة الكهربية بها مصدر (active) وتعمل استجابة لتغير ما تحت تأثير الطاقة المختزنة.

② step response.

* تعرفت الدائرة الكهربية لتغير ما بعد أن كان ثابتاً.

③ AC response.

* لو المصدر كان (AC) بعد أن كان المصدر = عصفر. ومتى شرط أن الموجة تكون (sinwave) فقط



* Any differential equation has four elements:-

① Independent variable.

متغير عشوائي (المتغير علىه التأثير)

$$(t) \leftarrow \frac{di}{dt}$$

② Dependent variable

معلومات المتغير التابع، وتقافلاته.

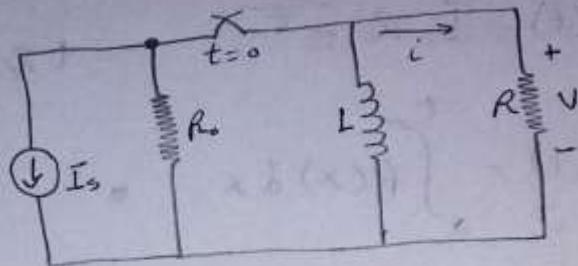
③ Parameters or Coefficients.

ـ \rightarrow اللحظة التي تطبق تغير حالة الـ switch مباشرة.

ـ \rightarrow اللحظة التي تلي تغير حالة الـ switch مباشرة.

Natural Response of First Order RL circuit

* قبل فتح المفتاح كانت الدائرة مستقرة
فكأن التيار I_s يمر بالكامل في الملف فتكون
الطاقة المخزنة $(\frac{1}{2}L_i^2)$

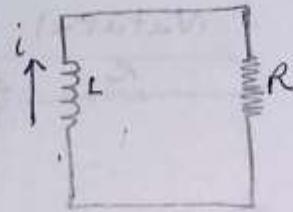


at : $t < 0$

$$I_0 = I_s$$

at : $t \geq 0$

$$L \frac{di}{dt} + iR = 0$$



$$\frac{di}{dt} \propto \frac{-iR}{L}$$

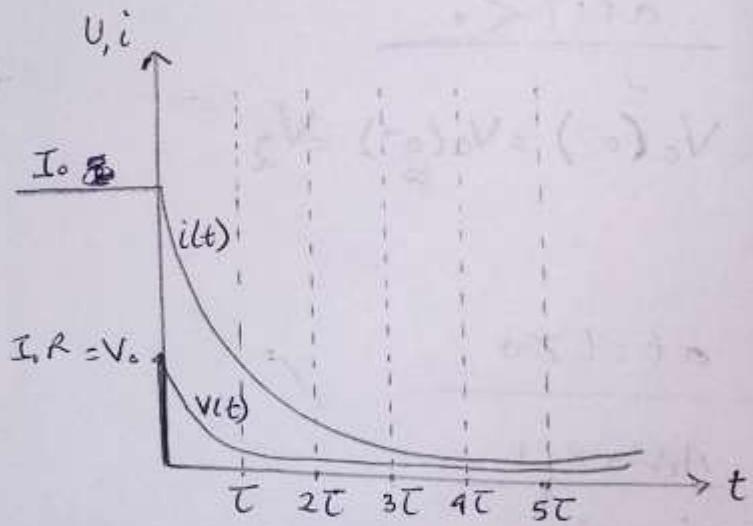
$$I_0 \int \frac{di}{i} = \int \frac{-R}{L} dt$$

$$\ln i(t) - \ln I_0 = \frac{-R}{L} t$$

$$\frac{i(t)}{I_0} \propto e^{\frac{-R}{L}t}$$

$$i(t) = I_0 e^{\frac{-t}{\tau}} \quad t \geq 0$$

$$v(t) = I_0 R e^{-t/\tau} \quad t \geq 0$$



$$\tau = \frac{L}{R}$$

$$P = Vi$$

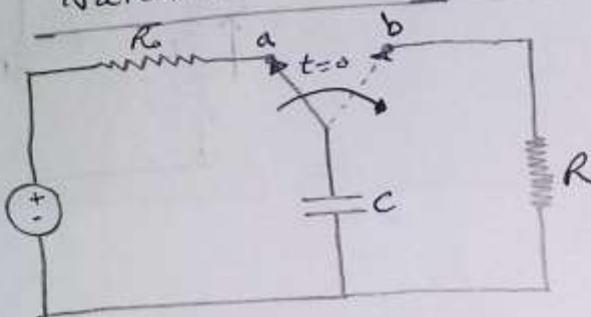
$$P(t) = I^2 R e^{-\frac{2t}{T}}$$

$$W(t) = \int_0^t P(x) dx$$

$$W(t) = \frac{T}{2} I_0^2 R (1 - e^{-\frac{2t}{T}})$$

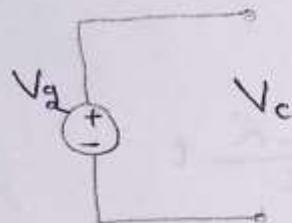
$$W(\infty) = \frac{T}{2} I_0^2 R = \frac{1}{2} L I_0^2$$

Natural response of RC circuit



at: $t < 0$

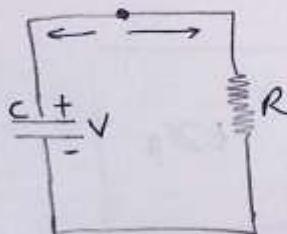
$$V_c(0^-) = V_c(0^+) = V_2$$



at: $t \geq 0$

Apply KCL

$$i_R + i_C = 0$$



$$C \frac{dV}{dt} + \frac{V}{R} = 0$$

$$\frac{dV}{dt} = \frac{-V}{RC}$$

[5]

$$\int_{V_c(0)}^{V(t)} \frac{dV}{V} = \int_0^t \frac{-1}{RC} dt$$

$$\ln V(t) - \ln V_c(0) = \frac{-t}{RC}$$

$$\frac{V(t)}{V_c(0)} = e^{-t/\tau}$$

$$\tau = RC$$

$$V(t) = V_c(0) e^{-t/\tau} \quad t \geq 0$$

$$i(t) = \frac{V_c(t)}{R} = \frac{V_c(0)}{R} e^{-t/\tau}$$

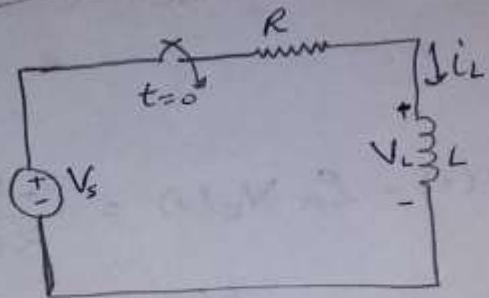
$$P(t) = i^2(t) R = \frac{V_c(0)^2}{R} e^{-2t/\tau}$$

$$w(t) = \int_0^t P(t) dt$$

$$w(t) = \frac{1}{2} C V_0^2 (1 - e^{-2t/\tau})$$

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Step response of an RL circuit



At $t < 0$

$$i_L(0) = I_0$$

at $t \geq 0$

Apply KVL

$$V_s = iR + L \frac{di}{dt}$$

$$\frac{di}{dt} + \frac{V_s - iR}{L} = \frac{-R}{L} \left(i - \frac{V_s}{R} \right)$$

$$I_0 \int \frac{di}{i - \frac{V_s}{R}} = \int \frac{-R}{L} dt$$

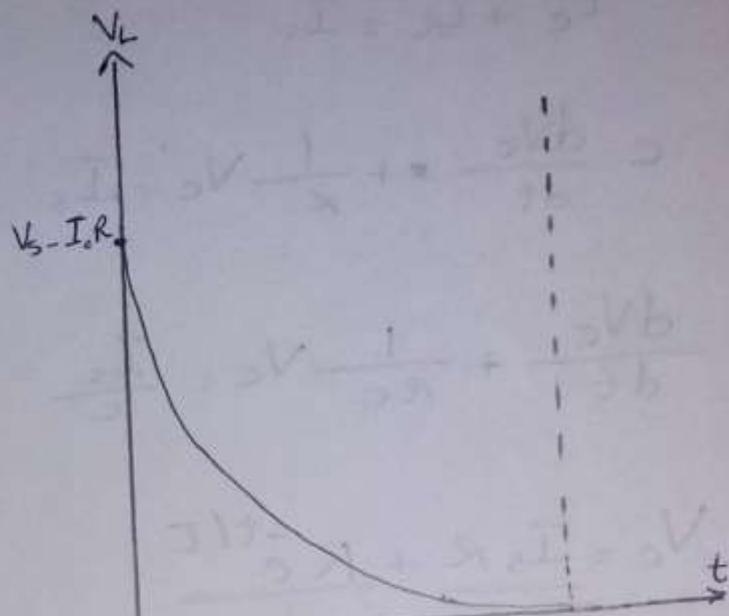
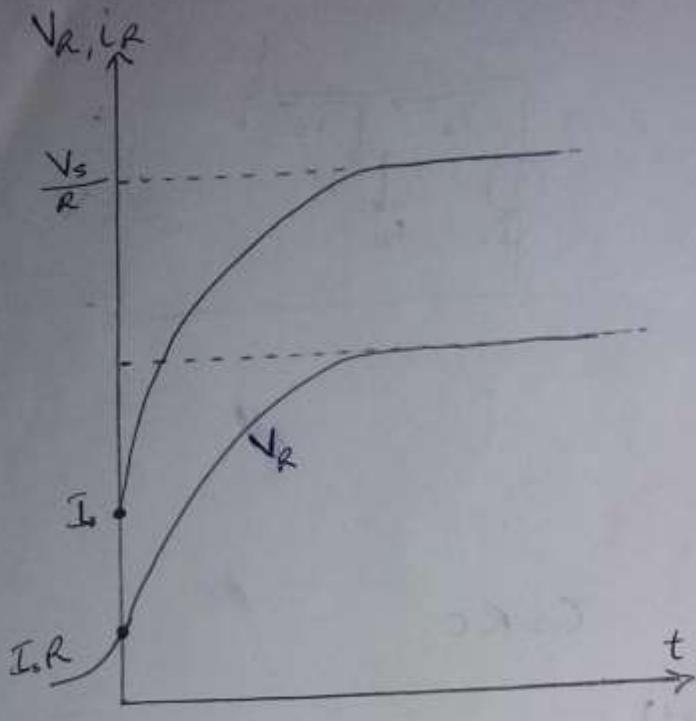
$$i(t) = \frac{V_s}{R} + \left(I_0 + \frac{V_s}{R} \right) e^{-t/\tau}$$

$$\tau = \frac{L}{R}$$

$$\text{if } I_0 = 0 \Rightarrow i(t) = \frac{V_s}{R} \left(1 - e^{-t/\tau} \right)$$

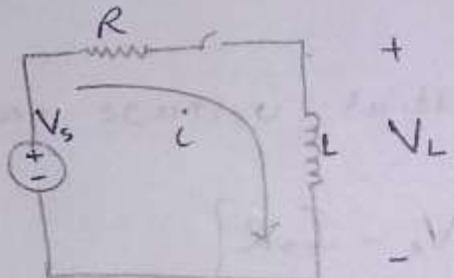
$$V_L = L \frac{di}{dt} = (V_s - I_0 R) e^{-t/\tau}$$

$$V_R = V_s + (I_0 R - V_s) e^{-t/\tau}$$



Another case

$$i = \frac{V_s - V_L}{R}$$



$$\frac{di}{dt} = -\frac{1}{R} \frac{dV_L}{dt}$$

$$L \frac{di}{dt} = -\frac{L}{R} \frac{dV_L}{dt}$$

$$V_L = \frac{-L}{R} \frac{dV_L}{dt}$$

$$V_L(0) = V_s - I_0.R$$

$\therefore V_L = K e^{-t/\tau}$

Step Response of an RC circuit

$$i_C + i_R = I_s$$

$$C \frac{dV_c}{dt} + \frac{1}{R} V_c = I_s$$

$$\frac{dV_c}{dt} + \frac{1}{RC} V_c = \frac{I_s}{C}$$

$$V_c = I_s R + \frac{K e^{-t/\tau}}{\tau} \quad \tau = RC$$

(steady state) (+transient)

* using initial voltage on capacitor (V_0) [is considered]

$$K = [V_0 - I_s R]$$

$$V_c = I_s R + (V_0 - I_s R) e^{-t/\tau}$$

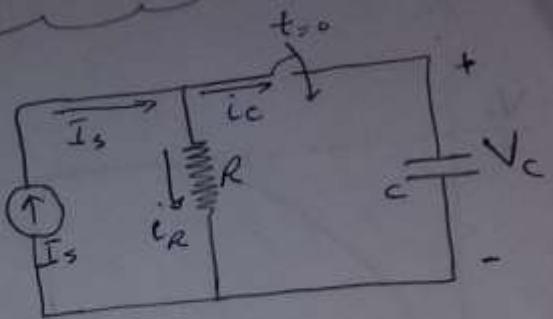
$t \gg \tau \rightarrow *$

For zero I.C (Initial condition)

$$V_c = I_s R (1 - e^{-t/\tau})$$

$$i_C = C \frac{dV_c}{dt} \quad (\text{General case})$$

$$i_C = (I_s - \frac{V_0}{\tau}) e^{t/\tau} \quad t > 0$$



$$V_{CSR} = (I_s - i_c)R$$

$$\frac{dV_c}{dt} = -R \frac{di_c}{dt} \quad *C$$

$$C \frac{dV_c}{dt} = -RC \frac{di_c}{dt}$$

$$i_c = -RC \frac{di_c}{dt}$$

$$\frac{di_c}{dt} + \frac{1}{RC} i_c = 0$$

From * we can get General form.

$$A(t) = A(\infty) + [A(0^+) - A(\infty)] e^{-t/\tau}$$

General solution

$$\frac{dx}{dt} + \frac{1}{\tau} x = K \quad x(t=t_0) = x_0$$

$$x = x_{ss} + x_t$$

$$x_{ss}: \frac{dx}{dt} = 0 \Rightarrow x_{ss} = K\tau$$

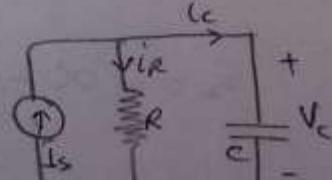
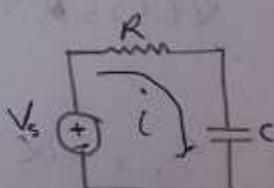
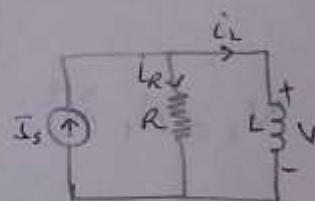
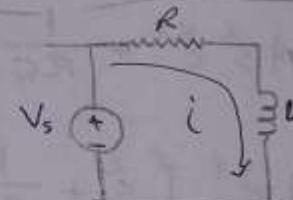
$$x_t = A e^{-(t-t_0)/\tau} = K\tau + A e^{-(t-t_0)/\tau}$$

$$\therefore x(t) = x_p + (x_0 - x_p) e^{-(t-t_0)/\tau}$$

محلل المدار
معادلة الماس

we need:

$$x_p = I_s R \quad x_p = V_c / C$$



Natural response of parallel RLC

at m

$$i_R + i_L + i_C + I_0 = 0$$

$$\frac{V}{R} + \frac{1}{L} \int V dt + C \frac{dV}{dt} + I_0 = 0$$

جاء جواب المقاومات بالنسبة t

$$\frac{1}{R} \frac{dV}{dt} + \frac{V}{L} + C \frac{d^2 V}{dt^2} = 0$$

$$V(0) = V_0, \quad i_L(0) = I_0$$

$$\boxed{\frac{d^2 V}{dt^2} + \frac{1}{RC} \frac{dV}{dt} + \frac{1}{LC} V = 0}$$

$$V = A e^{st}, \quad \frac{dV}{dt} = A s e^{st}, \quad \frac{d^2 V}{dt^2} = A s^2 e^{st}$$

$$A s^2 e^{st} + \frac{1}{RC} A s e^{st} + \frac{1}{LC} A e^{st} = 0$$

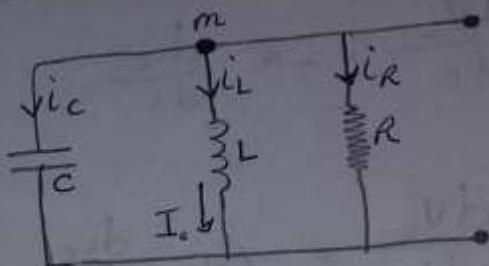
$$A e^{st} \left(s^2 + \frac{1}{RC} s + \frac{1}{LC} \right) = 0$$

$$V_1 = A_1 e^{s_1 t}, \quad V_2 = A_2 e^{s_2 t}$$

$$V(t) = A V_1 + V_2 = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2}$$

$$s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2}$$



Where:

$$\alpha = \frac{1}{2RC} \rightarrow \text{reference frequency}$$

rad/sec

$$\omega_0 = \frac{1}{\sqrt{LC}} \rightarrow \text{resonance frequency}$$

① $\alpha > \omega_0 \rightarrow$ "over damped"

(s_1, s_2 real and distinct)

$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

② $\alpha < \omega_0 \rightarrow$ "under damped"

(s_1, s_2 complex and conjugated)

$$v(t) = \bar{e}^{\alpha t} (B_1 \cos(\omega_d t) + B_2 \sin(\omega_d t))$$

where: $\omega_d = \sqrt{\omega_0^2 - \alpha^2} \rightarrow$ damped radian frequency

③ $\alpha = \omega_0 \rightarrow$ "critically damped"

(s_1, s_2 real and equal)

$$v(t) = D_1 t \bar{e}^{-\alpha t} + D_2 \bar{e}^{-\alpha t}$$

① over damped response (proof) ($\alpha > \omega_0$)

$$V(t) = A_1 e^{S_1 t} + A_2 e^{S_2 t}$$

$A_1, A_2 \rightarrow$ initial condition, $V_0(0^+) \rightarrow$ initial voltage of capacitor.

$$\frac{dV}{dt}(0^+) = \frac{C_c(0^+)}{C} = \frac{-i_L(0^+) - i_R(0^+)}{C} = \frac{-i_L(0^+) - \frac{V(0^+)}{R}}{C}$$

$$\frac{dV}{dt}(0^+) = A_1 S_1 + A_2 S_2$$

$$V(0^+) = A_1 + A_2$$

② critically damped

$$\alpha = \omega_0$$

$$S_1 = S_2 = -\alpha = \frac{-1}{2RC}$$

$$V(t) = D_1 t e^{-\alpha t} + D_2 e^{-\alpha t}$$

$$V(0^+) = D_2$$

$$\frac{dV}{dt}(0^+) = D_1 - \alpha D_2$$

② under damped ($\alpha < \omega_0$)

$$S_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

$$= -\alpha \pm \sqrt{\omega_0^2 - \alpha^2} = -\alpha \pm j\omega_d$$

where: $\omega_d = \sqrt{\omega_0^2 - \alpha^2} \rightarrow$ damped radian frequency

$$v(t) = A_1 e^{S_1 t} + A_2 e^{S_2 t} = A_1 e^{(-\alpha + j\omega_d)t} + A_2 e^{(-\alpha - j\omega_d)t}$$

$$= A_1 e^{-\alpha t} e^{j\omega_d t} + A_2 e^{-\alpha t} e^{-j\omega_d t}$$

$$e^{\pm j\theta} = \cos \theta \pm j \sin \theta$$

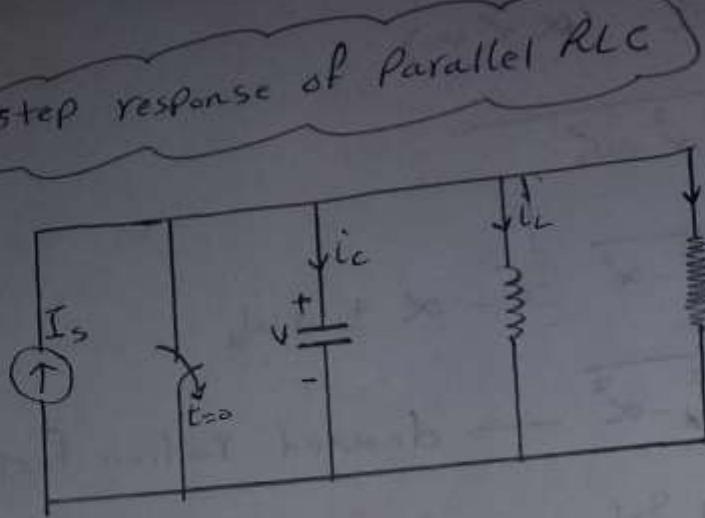
$$v(t) = A_1 e^{-\alpha t} (\cos(\omega_d t) + j \sin(\omega_d t)) + A_2 e^{-\alpha t} (\cos(\omega_d t) - j \sin(\omega_d t))$$

$$v(t) = e^{-\alpha t} \left[\underbrace{(A_1 + A_2)}_{B_1} \cos(\omega_d t) + \underbrace{j(A_1 - A_2)}_{B_2} \sin(\omega_d t) \right]$$

$$v(t) = e^{-\alpha t} [B_1 \cos(\omega_d t) + B_2 \sin(\omega_d t)]$$

$$v(0^+) = B_1$$

$$\frac{dv}{dt}(0^+) = -\alpha B_1 + \omega_d B_2$$



At $t \neq 0$

Apply KCl

$$I_s = i_C + i_R + i_L$$

$$I_s = C \frac{dV}{dt} + \frac{V}{R} + \frac{1}{L} \int V dt + I_0$$

$$0 = \frac{Cd^2V}{dt^2} + \frac{V}{L} + \frac{1}{R} \frac{dV}{dt} = 0$$

$$\frac{d^2V}{dt^2} + \frac{1}{LC}V + \frac{1}{RC} \frac{dV}{dt} = 0$$

$$V = A e^{st}, \quad \frac{du}{dt} = A s e^{st}, \quad \frac{d^2 u}{dt^2} = A s^2 e^{st}$$

$$A \stackrel{st}{\in} \left(s^2 + \frac{1}{RC} s + \frac{1}{LC} \right) =$$

$$S_{1,2} = \frac{-1}{2RC} \pm \sqrt{\left(\frac{1}{2RC}\right)^2 + \frac{1}{LC}}$$

- Case
- ① $\alpha > \omega_0 \rightarrow$ over damped $\Rightarrow V(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$
 - ② $\alpha < \omega_0 \rightarrow$ under damped $\Rightarrow V(t) = \bar{e}^{\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t)$
 - ③ $\alpha = \omega_0 \rightarrow$ critically damped $\Rightarrow V(t) = D_1 t \bar{e}^{\alpha t} + D_2 \bar{e}^{\alpha t}$

$$i_L(t) = I_s + \begin{cases} A_1 e^{s_1 t} + A_2 e^{s_2 t} & \rightarrow \text{over damped} \\ (B_1 \cos(\omega_d t) + B_2 \sin(\omega_d t)) \bar{e}^{\alpha t} & \rightarrow \text{under damped} \\ D_1 t \bar{e}^{\alpha t} + D_2 \bar{e}^{\alpha t} & \rightarrow \text{critically damped} \end{cases}$$

$$i_R(t) = \frac{V(t)}{R} = \underbrace{\left(\frac{A_1}{R} \right)}_{\gamma A_1} e^{s_1 t} + \underbrace{\left(\frac{A_2}{R} \right)}_{\gamma A_2} e^{s_2 t} + 0$$

General form

$$A(t) = A(\infty) + \begin{cases} A_1 e^{s_1 t} + A_2 e^{s_2 t} \\ \bar{e}^{\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t) \\ D_1 t \bar{e}^{\alpha t} + D_2 \bar{e}^{\alpha t} \end{cases}$$

$$i_L(t) = I_F + A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$i_L(\infty) = i_F + A_1 + A_2$$

$$\frac{d i_L(\sigma^+)}{d\sigma^+} = \frac{V_L(\sigma^+)}{L} = A_1 s_1 + A_2 s_2$$

$$i_L(\infty) = I_F$$

$$V_C(\infty) = 0$$

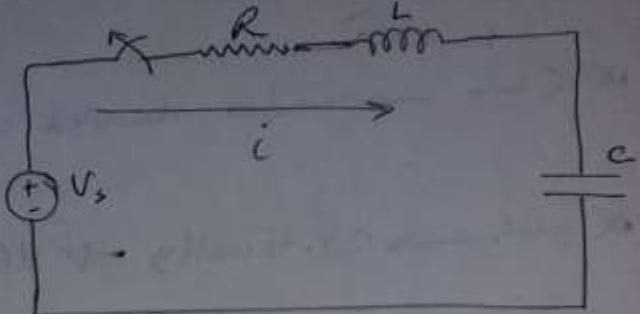
$$i_L = \frac{1}{L} \int_0^t V(t) dt + I_0$$

Natural and steady response of series RLC circuits

At $t = 0$

$$V_R + V_L + V_C = 0$$

$$iR + L \frac{di}{dt} + \frac{1}{C} \int_0^t i dt + V_s = 0$$



$$\frac{L di^2}{dt} + \frac{i}{C} + \frac{R di}{dt} = 0$$

$$\boxed{\frac{d^2 i}{dt^2} + \frac{R}{L} \frac{di}{dt} + \frac{1}{LC} i = 0}$$

$$i = A e^{st}, \quad \frac{di}{dt} = A s e^{st}, \quad \frac{d^2 i}{dt^2} = A s^2 e^{st}$$

$$A s^2 e^{st} + \frac{R}{L} A s e^{st} + \frac{1}{LC} A e^{st} = 0$$

$$A e^{st} \left(s^2 + \frac{R}{L} s + \frac{1}{LC} \right) = 0$$

ch/s

$$\zeta_{1,2} = \frac{-R}{2L} \pm \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}}$$

$$\zeta_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

$$\alpha = \frac{R}{2L}, \quad \omega_0 = \frac{1}{\sqrt{LC}}$$

$$\alpha > \omega_0 \rightarrow over \Rightarrow i(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

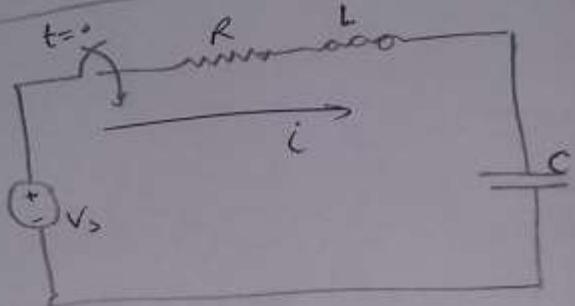
$$\alpha < \omega_0 \rightarrow under \Rightarrow i(t) = e^{\alpha t} (B_1 \cos \omega_0 t + B_2 \sin \omega_0 t)$$

$$\alpha = \omega_0 \rightarrow critically \Rightarrow i(t) = D_1 t e^{-\alpha t} + D_2 e^{-\alpha t}$$

$$V_L = L \frac{di}{dt}, \quad V_C = \frac{1}{C} \int_0^t i dt + V_0, \quad V_R = iR$$

Step response of series RLC

$$V_s = V_R + V_L + V_C$$



$$V_s = iR + L \frac{di}{dt} + \frac{1}{C} \int_0^t i dt + V_0$$

$$0 = L \frac{d^2 i}{dt^2} + R \frac{di}{dt} + \frac{i}{C} = 0$$

$$\boxed{\frac{d^2 i}{dt^2} + \frac{R}{L} \frac{di}{dt} + \frac{1}{LC} \cdot i = 0}$$

C چنانچه نسبتی دارد
Natural ۱۱

$$A(t) = A_p + \begin{cases} A_1 e^{s_1 t} + A_2 e^{s_2 t} \\ B_1 e^{-\alpha t} \cos \omega_0 t + B_2 e^{-\alpha t} \sin \omega_0 t \\ D_1 t e^{-\alpha t} + D_2 e^{-\alpha t} \end{cases}$$

Ch : 3

3-phase

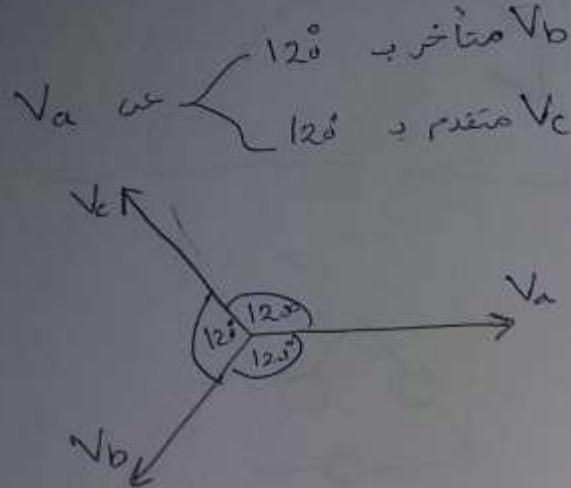
~~Ch. 3~~

Three Phase Circuits

Balanced three phase voltages

عباره عن ثلاثة فلاته في نفس المدة \Rightarrow $V_a = V \cos \phi$ و $V_b = V \cos (\phi - 120^\circ)$ و $V_c = V \cos (\phi + 120^\circ)$

\Rightarrow $+ve$ sequence (abc)

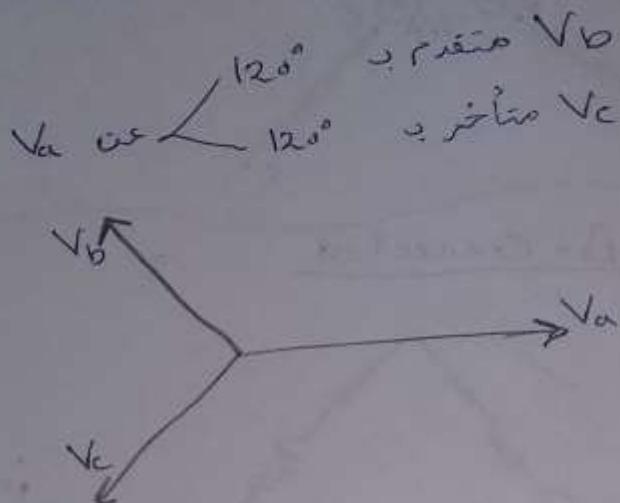


$$V_a = |V\phi| \angle 0^\circ$$

$$V_b = |V\phi| \angle -120^\circ$$

$$V_c = |V\phi| \angle 120^\circ$$

$\Rightarrow -ve$ sequence (acb)



$$V_a = |V\phi| \angle 0^\circ$$

$$V_b = |V\phi| \angle 120^\circ$$

$$V_c = |V\phi| \angle -120^\circ$$

$$V_a + V_b + V_c = 0 \quad \text{at } 120^\circ \text{ phase shift}$$

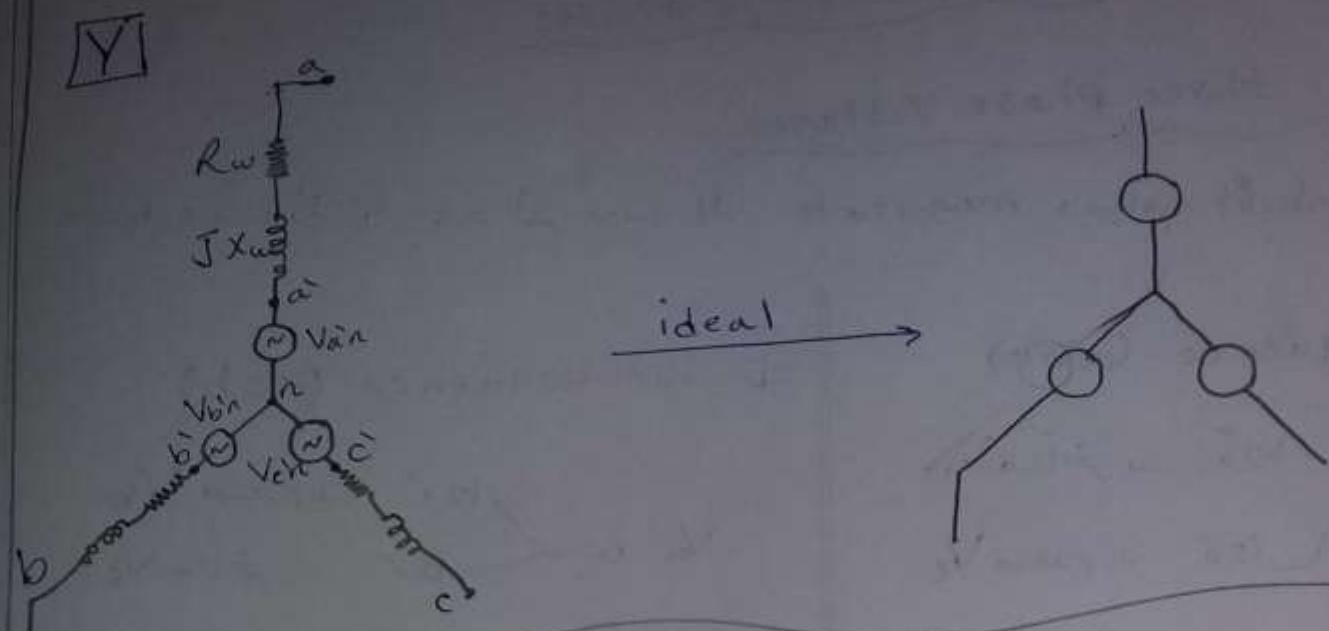
-magnitude \Rightarrow ①

Balanced شرط ②

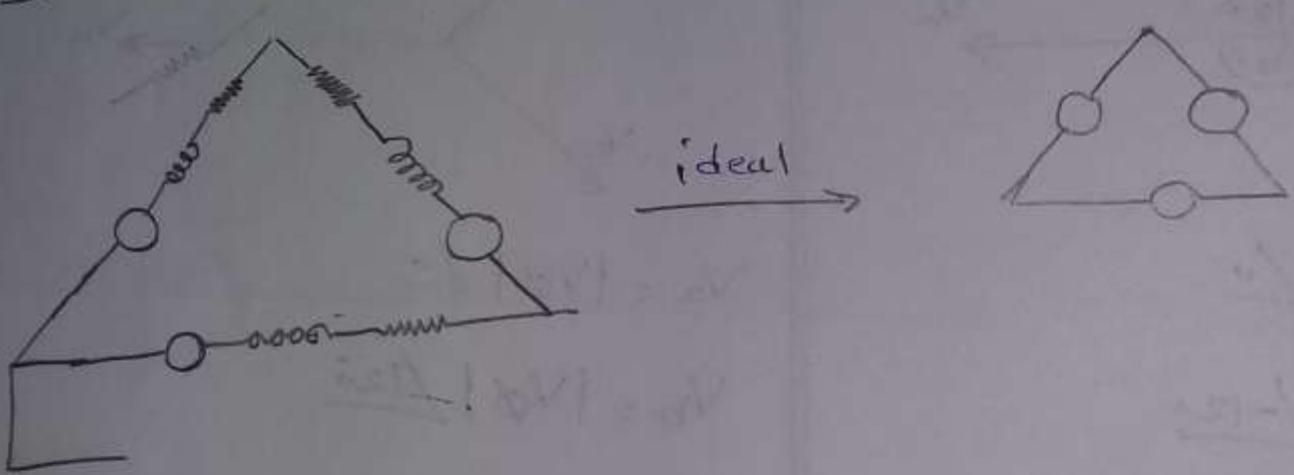
* 3 ϕ - voltage source

1 Y-connected -

2 Δ-connected -



Δ - Connected



* They are :

source → load

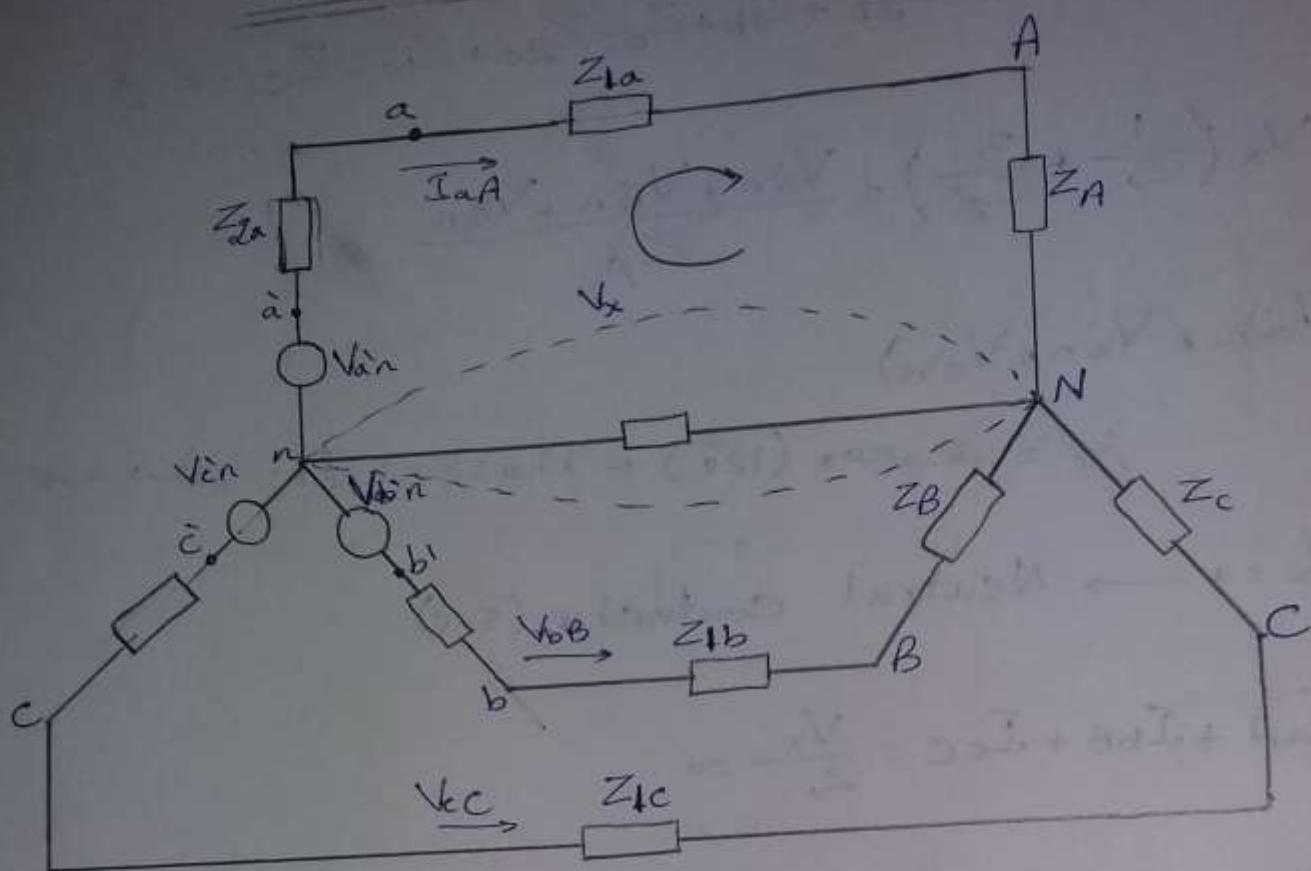
① Y - Y

② Y - Δ

③ Δ - Y

④ Δ - Δ

Y-Y Connected



$$I_o = I_{aA} + I_{bB} + I_{cC}$$

$$= \frac{V_{an} - V_x}{Z_{2a} + Z_{1a} + Z_A} + \frac{V_{bn} - V_x}{Z_{2b} + Z_{1b} + Z_B} + \frac{V_{cn} - V_x}{Z_{2c} + Z_{1c} + Z_C}$$

For balanced system:

$$V_a = V_b = V_c = 0$$

$$Z_{2a} = Z_{2b} = Z_{2c}$$

$$Z_A = Z_B = Z_C$$

$$Z_{1a} = Z_{1b} = Z_{1c}$$

$$Z_{2a} + Z_{1a} + Z_A = Z_{2b} + Z_{1b} + Z_B = Z_{2c} + Z_{1c} + Z_C = Z_\phi$$

$$V_x \left(\frac{1}{Z_0} + \frac{3}{Z_\phi} \right) = \frac{V_{an} + V_{bn} + V_{cn}}{Z_\phi}$$

(V_{an} , V_{bn} , V_{cn})

فلا ظهور جيئن \Rightarrow $\text{Phase shift} = 120^\circ$

$V_x = 0 \rightarrow \text{Neutral conductor (s.c.)}$

$$I_{aA} + I_{bB} + I_{cC} = \frac{V_x}{Z_0} = 0$$

\therefore Currents are also balanced.

if \rightarrow +ve sequence

$$V_{AN} = 2 \angle 15^\circ$$

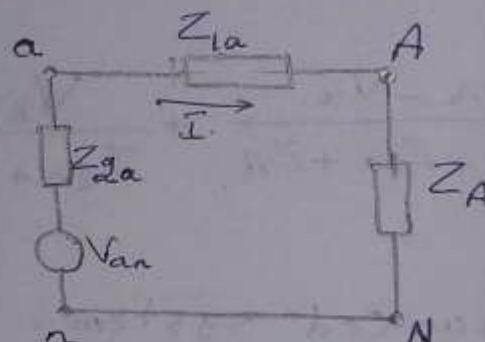
$$V_{BN} = 2 \angle -105^\circ$$

$$V_{CN} = 2 \angle 135^\circ$$

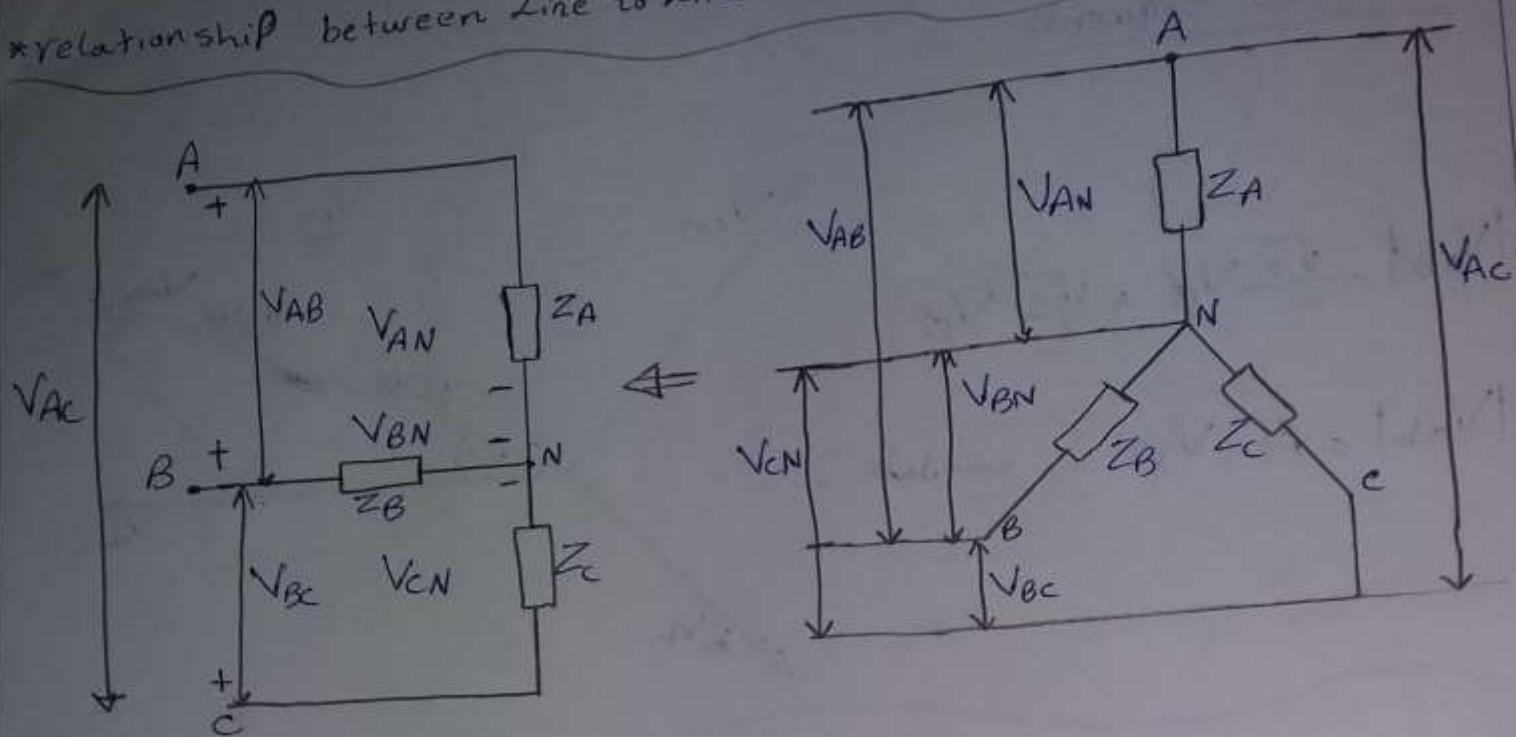
if \rightarrow -ve sequence

$$V_{AN} = 2 \angle 115^\circ$$

$$V_{BN} = 2 \angle 135^\circ$$



* Relationship between Line to Line Voltages and Phase Voltages:



$$V_{AB} - V_{AN} + V_{BN} = 0$$

$$V_{AB} = V_{AN} - V_{BN}$$

$$V_{BC} = V_{BN} - V_{CN}$$

$$V_{CA} = V_{CN} - V_{AN}$$

$$V_{AB} = V_{AN} - V_{BN} = \sqrt{\phi} \angle 0^\circ - \sqrt{\phi} \angle -120^\circ$$

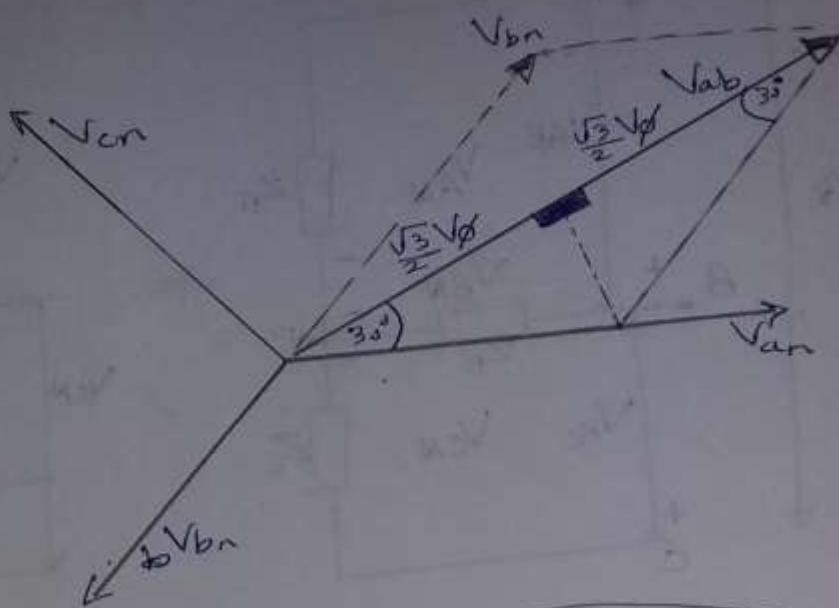
$$V_{AB} = \sqrt{3} \sqrt{\phi} \angle 30^\circ \rightarrow \text{for +ve sequence.}$$

$$\star V_{AB} = \sqrt{3} \sqrt{\phi} \angle -30^\circ \rightarrow \text{for -ve sequence.}$$

for +ve sequence

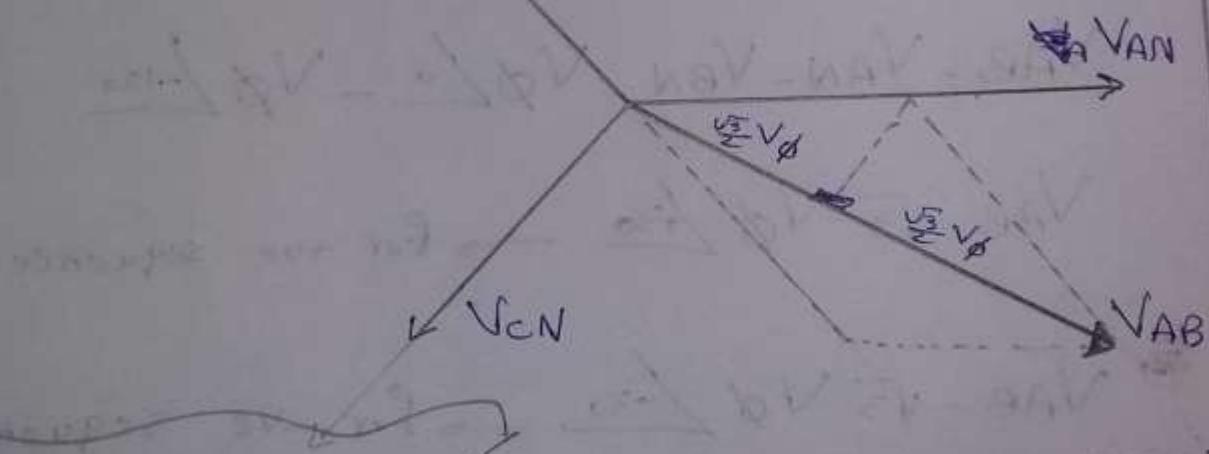
$$|V_{AB}| = \frac{\sqrt{3}}{2} V\phi + \frac{\sqrt{3}}{2} V\phi$$

$$|V_{AB}| = \sqrt{3} V\phi \quad \text{طبل متبع}$$



-ve sequence

$$|V_{AB}| = \cancel{\sqrt{3}} V\phi$$



V_{AN} :

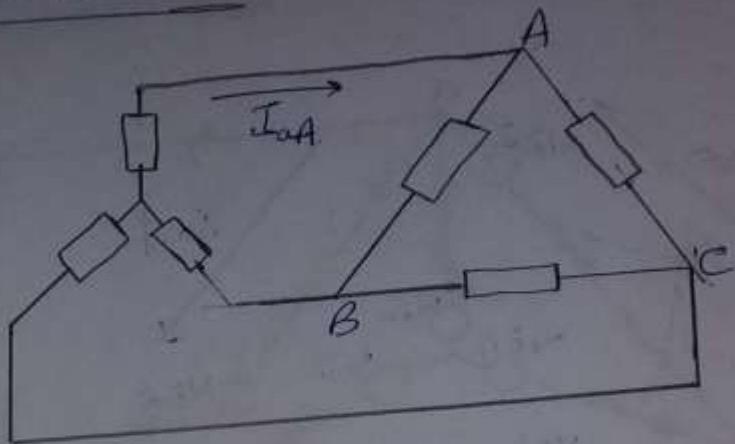
$$\sqrt{3} V\phi = \sqrt{3} V_{AN} \angle +30^\circ \rightarrow +ve$$

$$\sqrt{3} V\phi = \sqrt{3} V_{AN} \angle -30^\circ \rightarrow -ve$$

[6]

Y - Δ Connected

$$Z_Y = \frac{Z_\Delta}{3}$$



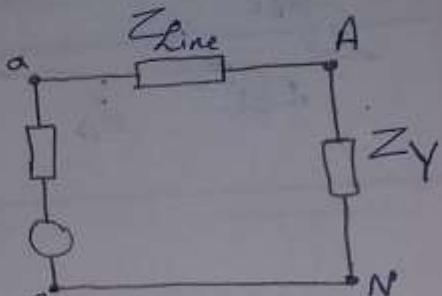
Δ

$$I_L \neq I_\phi$$

$$V_L = V_\phi$$

Y

$$I_L = I_\phi \quad V_L \neq V_\phi$$



*Phase voltage at terminals of load (V_{AB} , V_{BC} , V_{CA})

Apply KCL at node A

$$I_{aA} = I_{AB} - I_{cA}$$

$$= I_\phi \angle 0^\circ - I_\phi \angle 120^\circ$$

$$I_{aA} = \sqrt{3} I_\phi \angle -30^\circ$$

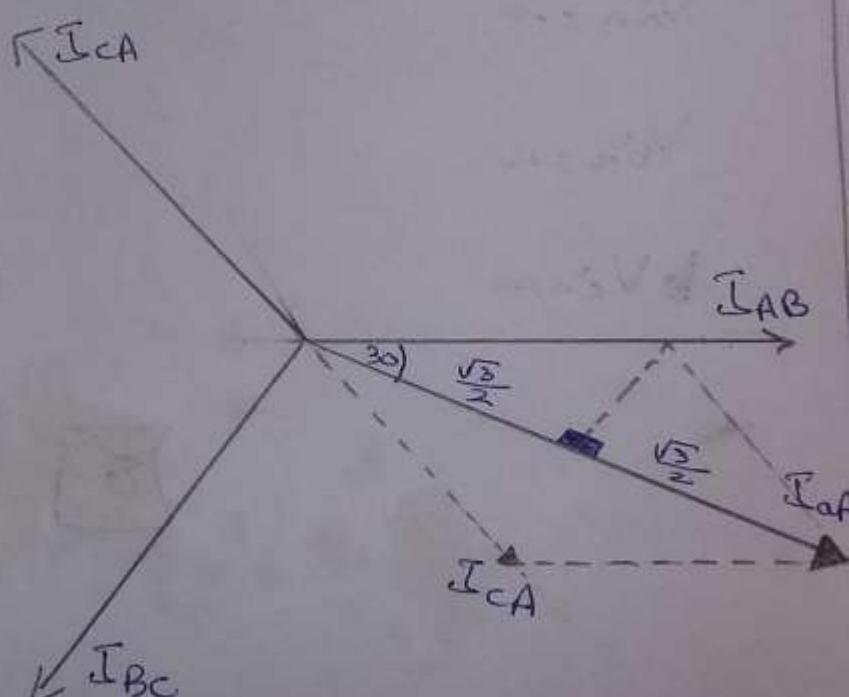
Line current

True seq.

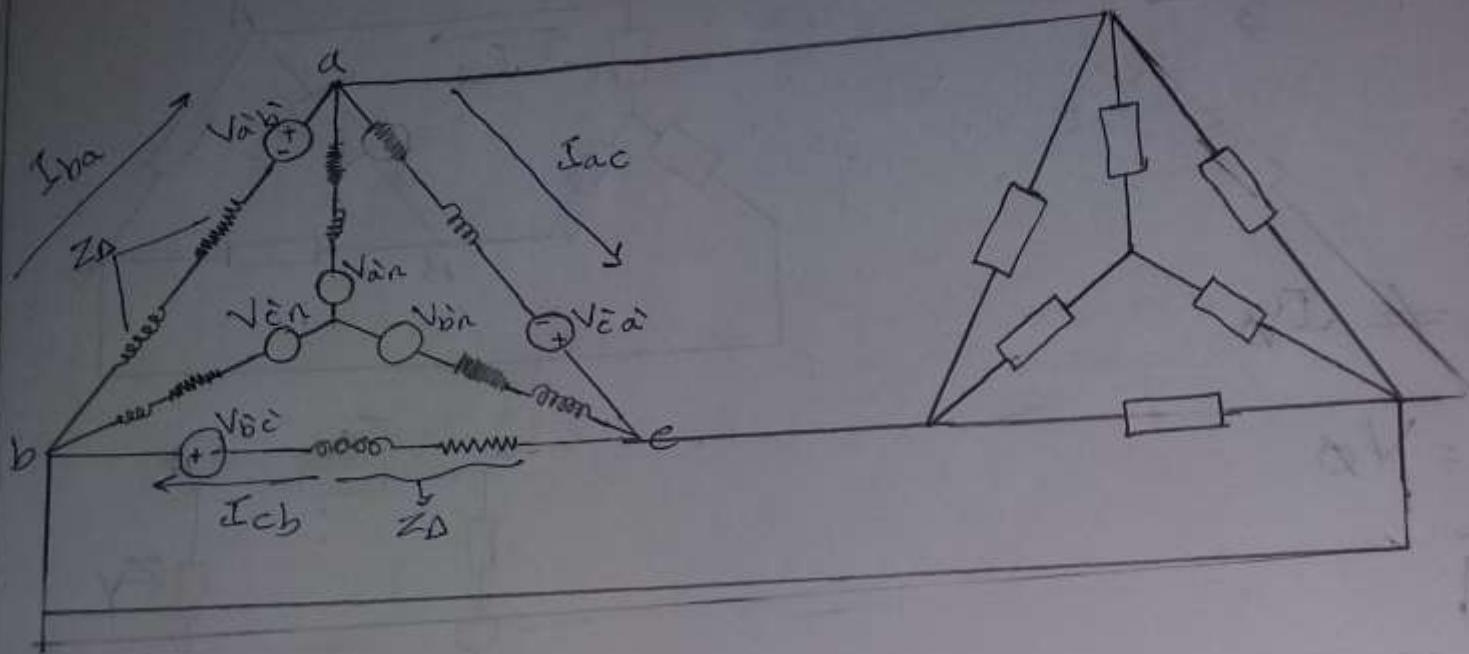
$$I_{AB} = I_\phi \angle 0^\circ$$

$$I_{BC} = I_\phi \angle -120^\circ$$

$$I_{cA} = I_\phi \angle 120^\circ$$



3) Δ/Y Connected



$$Z_Y = \frac{Z_\Delta}{3}$$

$$V_{ab} = \sqrt{3} V_{an} \angle +30^\circ$$

$$V_{an} = v$$

$$V_{bn} = v$$

$$V_{cn} = v$$

8

Power in circuits

For Y - Load

$$P_A = |V_{AN}| |I_{aA}| \cos(\theta_v - \theta_i)$$

$$P_B = |V_{BN}| |I_{bB}| \cos(\theta_v - \theta_i)$$

$$P_C = |V_{CN}| |I_{cC}| \cos(\theta_v - \theta_i)$$

For Balanced system

$$|V_{AN}| = |V_{BN}| = |V_{CN}| = V\phi$$

$$|I_{aA}| = |I_{bB}| = |I_{cC}| = I\phi$$

$$(\theta_v - \theta_i)_A = (\theta_v - \theta_i)_B = (\theta_v - \theta_i)_C = \theta\phi$$

$$\therefore P_A = P_B = P_C = V\phi I\phi \cos\theta\phi$$

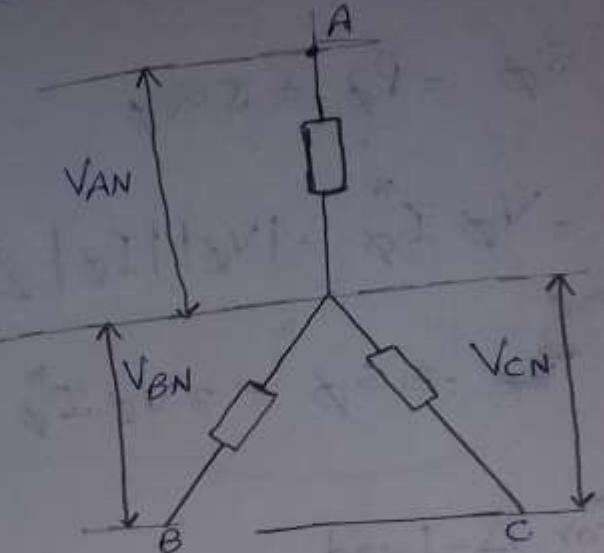
$$P_{3\phi} = P_A + P_B + P_C = 3V\phi I\phi \cos\theta\phi \quad \text{for Y}$$

$$= \sqrt{3} \sqrt{3} \frac{V_L}{\sqrt{3}} I_L \cos\theta\phi = \sqrt{3} V_L I_L \cos\theta\phi$$

*Reactive Power (Q)

$$Q_A = Q_B = Q_C = V\phi I\phi \sin\theta\phi$$

$$Q_{3\phi} = 3V\phi I\phi \sin\theta\phi = \sqrt{3} V_L I_L \sin\theta\phi \quad \text{VAR}$$



* Apparent Power (s)

$\rightarrow \text{Lag } (Q_L > Q_C)$

$$S_\phi = P_\phi + jQ_\phi$$

$\rightarrow \text{Lead } (Q_L < Q_C)$

$$= V_\phi I_\phi^* = |V_\phi| |I_\phi| \angle \pm \theta_i \quad \text{VA}$$

$S_3\phi$

~~$$S_3\phi = 3S_\phi = 3V_\phi I_\phi^*$$~~

For Δ -Load

$$P_{AB} = |V_{AB}| |I_{AB}| \cos(\theta_v - \theta_i)_{AB}$$

$$P_{BC} = |V_{BC}| |I_{BC}| \cos(\theta_v - \theta_i)_{BC}$$

$$P_{CA} = |V_{CA}| |I_{CA}| \cos(\theta_v - \theta_i)_{CA}$$

$$|V_{AB}| = |V_{BC}| = |V_{CA}| = V_\phi$$

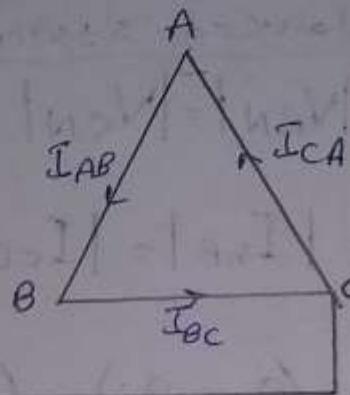
$$|I_{AB}| = |I_{BC}| = |I_{CA}| = I_\phi$$

$$(\theta_v - \theta_i)_{AB} = (\theta_v - \theta_i)_{BC} = (\theta_v - \theta_i)_{CA} = \theta_\phi$$

$$P_{AB} = P_{BC} = P_{CA} = P_\phi = V_\phi I_\phi \cos \theta_\phi$$

$$P_{3\phi} = 3P_\phi = 3V_\phi I_\phi \cos \theta_\phi$$

$$= \sqrt{3} V_L I_L \cos \theta_\phi$$



* Reactive Power (Q)

$$Q_{AB} = Q_{BC} = Q_{CA} = Q_\phi = V_\phi I_\phi \sin \theta_\phi$$

$$Q_{3\phi} = 3V_\phi I_\phi \sin \theta_\phi = \sqrt{3} V_L I_L \sin \theta_\phi$$

* Apparent Power (S)

$$S_\phi = P_\phi + jQ_\phi$$

$$S_{3\phi} = P_{3\phi} + jQ_{3\phi}$$

ملاحظة المعاوقة في أي مكثف
مع (3 Phase) \rightarrow (Power) كوكب
الكتل المترافق

نهاية!

* Instantaneous Power

$$P_A(t) = V_{AN}(t) * I_{aA}(t) = V_m \cos(\omega t) * I_m \cos(\omega t - \theta_\phi)$$

$$P_B(t) = V_m I_m \cos(\omega t - 120^\circ) \cos(\omega t + 120^\circ - \theta_\phi)$$

$$P_C(t) = V_m I_m \cos(\omega t + 120^\circ) \cos(\omega t - 120^\circ - \theta_\phi)$$

$$P_{3\phi}(t) = P_A + P_B + P_C = 1.5 V_m I_m \cos(\theta_\phi)$$

\hookrightarrow time invariant

$$\text{torque } \boxed{T = \frac{P}{\omega}} \rightarrow \text{time invariant}$$

$$= 3 \left(\frac{V_m}{\sqrt{2}} \right) \left(\frac{I_m}{\sqrt{2}} \right) \cos \theta_\phi = 3 V_\phi I_\phi \cos \theta_\phi$$

$$P_{3\phi} = \sqrt{3} V_L I_L \cos \theta_\phi$$

Ch : 4

Mutual inductance

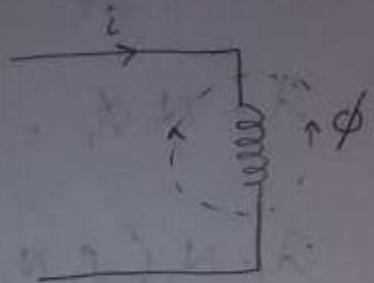
Ch. 4

Mutual inductance

أي مدة يغير تيار ينفاذ عن فیثون ϕ . (الجهاز يتم بعدها الميدان)

$$V = \frac{d\lambda}{dt}$$

$\lambda \rightarrow$ flux linkage



$$\lambda = N\phi$$

$$\phi = \mu Ni \quad \mu \rightarrow \text{Permeance}$$

هذا يعني أن سطح المليبار في المغناطيس \propto Ni

Magnetic materials

$$\mu \propto \phi$$

nonmagnetic

$$\mu \rightarrow \text{Constant } (\phi \propto i)$$

$$V = \frac{d\lambda}{dt} = \frac{d}{dt}(N^2 \mu i) = N^2 \mu \frac{di}{dt}$$

$$V = L \frac{di}{dt} \quad L \rightarrow \text{self inductance}$$

$$L = N^2 \mu$$

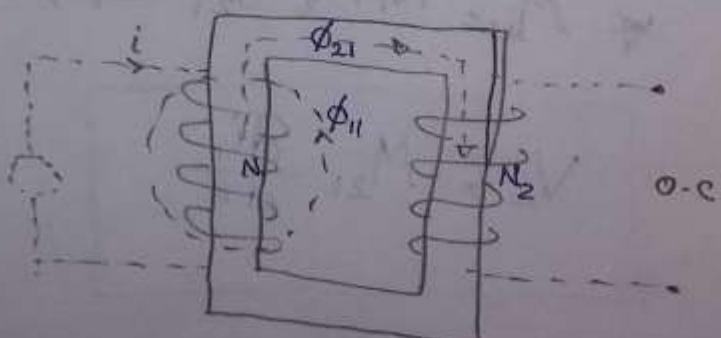
Mutual inductance (M)

هي أحد الparameters الذي يربط الجهد المعتنث على الملفتين بالتيار المار باللهم الآخر.

$$\phi_i = \phi_{ii} + \phi_{21} = N_1 \mu_1 i$$

$$\phi_{ii} = \mu_1 N_1 i$$

$$\phi_{21} = \mu_{21} N_1 i$$



$$V_1 = \frac{d\lambda_1}{dt}$$

$$\lambda_1 = N_1 \phi_1 = N_1 (\phi_{11} + \phi_{21})$$

$$\lambda_1 = N_1 (S_{11} N_1 i_1 + S_{21} N_1 i_1)$$

$$\lambda_1 = N_1^2 S_1 i_1$$

$$V_1 = N_1^2 S_1 \frac{di_1}{dt} = L_1 \frac{di_1}{dt}$$

$$V_2 = \frac{d\lambda_2}{dt} = N_2 \phi_2$$

$$\lambda_2 = N_2 \phi_{21}$$

$$\phi_{21} = S_{21} N_1 i_1$$

$$\lambda_2 = N_1 N_2 S_{21} i_1$$

$$V_2 = \frac{d}{dt} (N_1 N_2 S_{21} i_1)$$

$$V_2 = N_1 N_2 S_{21} \frac{di_1}{dt}$$

* الجهد المترتب على الملفات N_2 ناتج عن مرور التيار فيها

$$V_2 = M_{21} \frac{di_1}{dt}$$

$$V_2 = N_2 \Phi_2 \frac{di_2}{dt}$$

$$V_2 = L_2 \frac{di_2}{dt}$$

$$V_1 = N_1 N_2 \Phi_{12} \frac{di_2}{dt}$$

$$V_1 = M_{12} \frac{di_2}{dt}$$

$$M_{21} = N_1 N_2 \Phi_{21} \quad , \quad M_{12} = N_1 N_2 \Phi_{12}$$

$$\therefore \Phi_{21} = \Phi_{12}$$

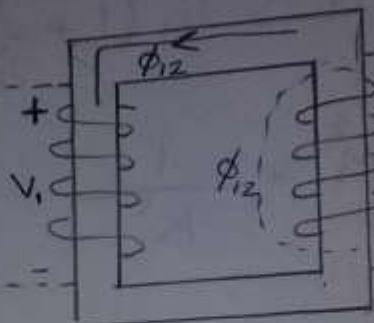
$$\therefore M_{21} = M_{12} = M$$

*relationship between L_1, L_2, M

$$L_1 = N_1^2 \Phi_1^2 = N_1 (\Phi_{11} + \Phi_{21})$$

$$L_2 = N_2^2 \Phi_2^2 = N_2 (\Phi_{22} + \Phi_{12})$$

$$L_1 L_2 = N_1^2 N_2^2 (\Phi_{11} + \Phi_{21})(\Phi_{12} + \Phi_{22})$$



$$L_1 L_2 = N_1^2 N_2^2 \frac{S_{21}^2}{S_{21}} \left(1 + \frac{S_{11}}{S_{21}}\right) \left(1 + \frac{S_{22}}{S_{21}}\right)$$

$$L_1 L_2 = M^2 * \frac{1}{K^2}$$

$K \rightarrow$ Mutual coupling.

$$0 \leq K \leq 1$$

$$M^2 = L_1 L_2 K^2$$

$$M = K \sqrt{L_1 L_2}$$

[1] if $K=0$

$\therefore M=0$ لا يوجد دخل بين الملفين

[2] if $K=1$

$$M = \sqrt{L_1 L_2}$$

أي أن كل الجيف القادم مستحوذ على ϕ_{21}

ملحوظة

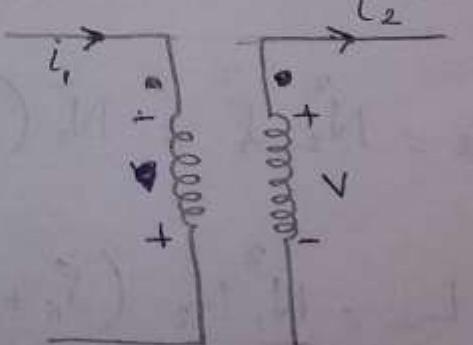
* أي ملفين يكون بينهم ربط (Coupling) ينبع على كل منهما (Mutual voltage)

* يتم تحديد الـ (Polarity) لـ (Mutual voltage) بواسطة دبوس (Dot marking)

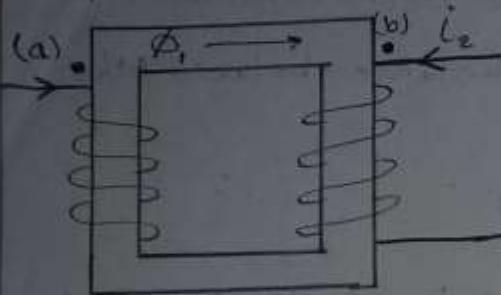
* إذا كان التيار i_1 داخلاً (Dot) بتاعة الملف

فإن (Polarity) تكمن على الملف الآخر (+) والعكس

يحدث مع i_2 .



كثافة حميدة (Polarity)



نحو ٣ بعزم تيار للأحمد داخل الملف

فتح (Dot) عند هذا التيار (عند a)

يشاهد إتجاه القطب مقابله للدالمن.

(A) لو ϕ_1, ϕ_2 في نفس الاتجاه فتح (Dot) يفتح (Dot) عند مكان دخول التيار للخلف الأيسر.

(B) لو ϕ_1, ϕ_2 متشوّق نفس الاتجاه فتح (Dot) يفتح (Dot) عند مكان خروج التيار للأسفل الأيسر.

Sheet

$$H_{max} = M_{max} \cdot 10^3 \text{ A/m}$$

$$25 \times 10^{-3}$$

$$25 \times 10^{-3} \text{ A/m}$$

$$H_{max} = 10^3 \text{ A/m}$$

sheet 4

Two magnetically coupled coils have self-inductance of 52 mH and 13 mH, respectively. The mutual inductance between the coils is 19.5 mH

- What is the coefficient of coupling?
- For these two coils, what is the largest value that M can have.
- The physical construction of four pairs of magnetically coupled coils is shown.
- Assume that the physical structure of these coupled coils is such that $\rho_1 = \rho_2$. What is the turn ratio $\frac{N_1}{N_2}$?

Solution

$$L_1 = 52 \text{ mH}, L_2 = 13 \text{ mH}, M = 19.5 \text{ mH}$$

$$a) K = \frac{M}{\sqrt{L_1 L_2}} = \frac{19.5 \times 10^{-3}}{\sqrt{52 \times 13 \times 10^{-6}}} = 0.75$$

$$b) \text{at } K = 1 \\ M_{\max} = \sqrt{L_1 L_2} = 26 \text{ mH}$$

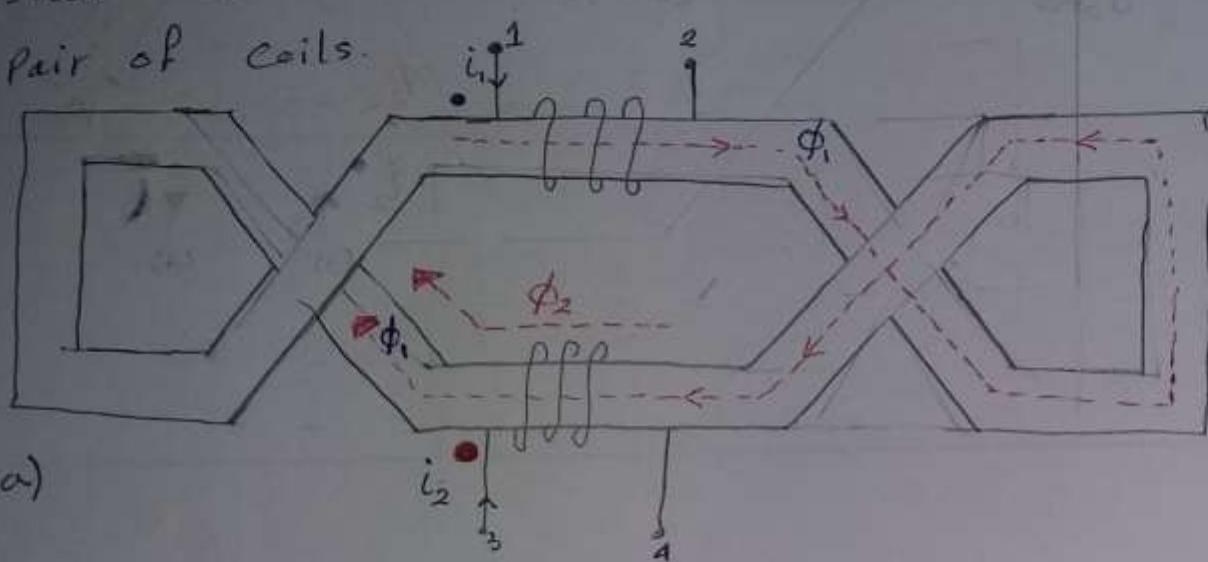
$$c) \rho_1 = \rho_2$$

$$L_1 = N_1^2 \rho_1^2 = 52 \quad , \quad L_2 = N_2^2 \rho_2^2 = 13$$

$$\frac{52}{13} = \frac{N_1^2}{N_2^2} = \frac{4}{1}$$

$$\therefore \frac{N_1}{N_2} = \frac{2}{1}$$

2 The physical construction of four pairs of magnetically coupled coils is shown in Fig. 1. Assume the magnetic flux is confined to the core material in each structure. Show the possible locations for the dot markings on each pair of coils.



a)

~~مما يلي~~

- ① نفع (dot+) عند مكان دخول التيار عند (1).
- ② نلاحظ أن ϕ_1 , ϕ_2 في نفس الاتجاه.
- ③ نفع (Dot) عند -(3) مكان دخول التيار.

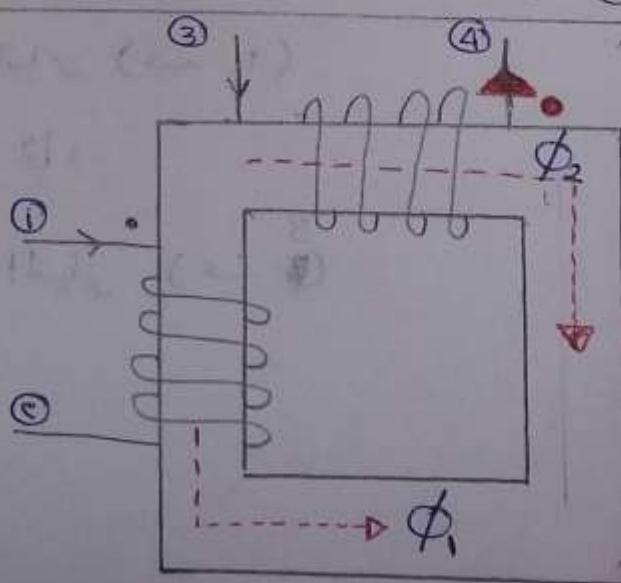
b)

نفترض (Dot+) عند مكان دخول التيار

فإن ϕ_2 , ϕ_1 في اتجاهين متقrossين.

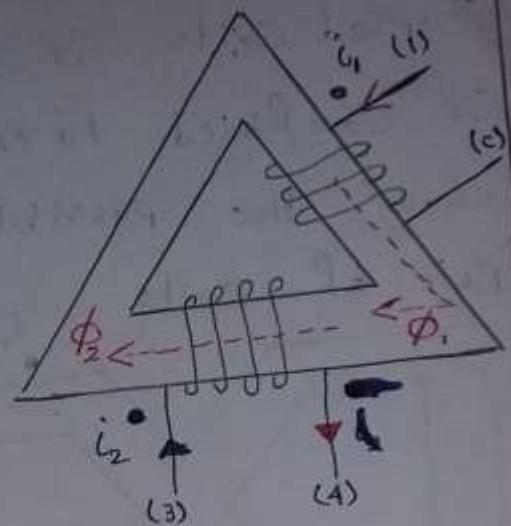
نفع (+) (Dot+) عند مكان خروج

التيار عند (4).

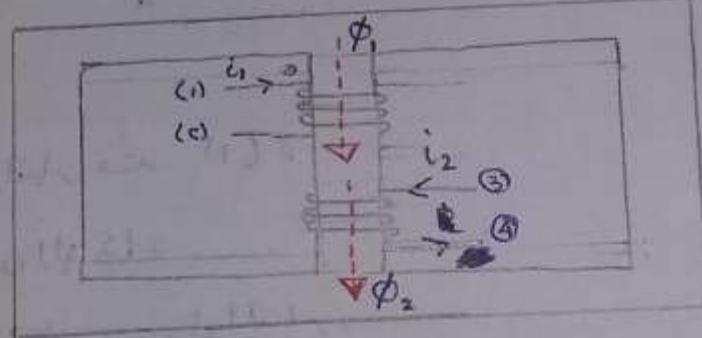


c)

- (a) نفع (0^o) عند مكان دخول التيار عند (1)
 (b) نلاحظ أن ϕ_1, ϕ_2 نفس الاتجاه
 (c) نفع (0^o) عند مكان دخول التيار عند (3).

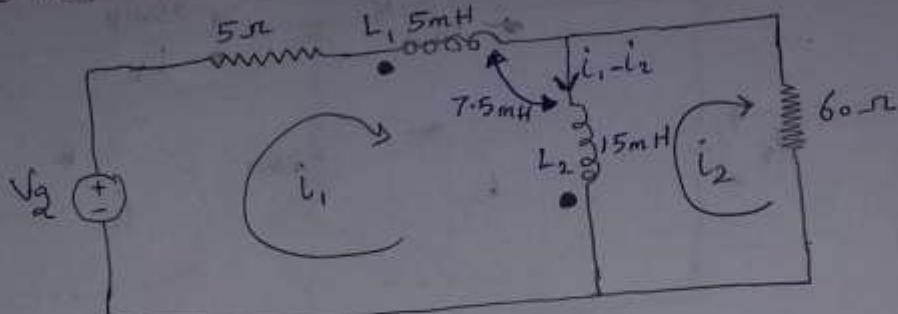


d)



(a) نفع (0^o) عند مكان دخول التيار (عند 1)

- (b) نلاحظ أن ϕ_1, ϕ_2 في نفس الاتجاه.
 (c) نفع (0^o) عند مكان دخول التيار (عند 3)



* دخربن نا زکرس حنا ضیکوه اللئار $(i_1 - i_2)$ خارج میه $(0\alpha + \beta\alpha)$ دستکو

$$\frac{M}{dt} d(i_1 - i_2)$$

(- +) L. μ (Polariz.) 33

$$(\text{Polariz}) \quad \text{على } L \text{ (+) } \rightarrow \text{ على } i_1 \text{ (+) } \leftarrow \text{ على } i_2 \text{ (+) } \rightarrow \text{ على } L \text{ (-)}$$

$\frac{dI}{dt} = -\frac{M d(i_1 - i_2)}{dt}$

$$-\frac{M d(i_1 - i_2)}{dt}$$

Equations

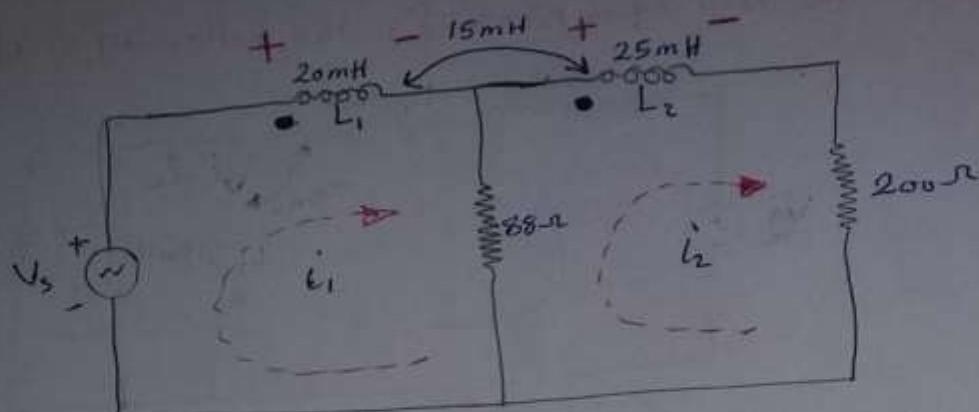
For Loop @

$$V_2 - 5i_1 - L_1 \frac{di_1}{dt} - M \frac{d(i_1 - i_2)}{dt} - L_2 \frac{d(i_1 - i_2)}{dt} + M \frac{di_2}{dt} = 0$$

for loop ②

$$-L_2 \frac{d(i_2 - i_1)}{dt} - M \frac{di_1}{dt} - 50i_2 = 0$$

b)



* التيار i_1 داخل لد L_1 و تكون الـ (Dot+) و تكون الـ (Dot+) i_2 بالمثل مع L_2

Equations

Variables

For Loop (1)

$$V_s - L_1 \frac{di_1}{dt} - M \frac{di_2}{dt} - 88(i_1 - i_2) = 0$$

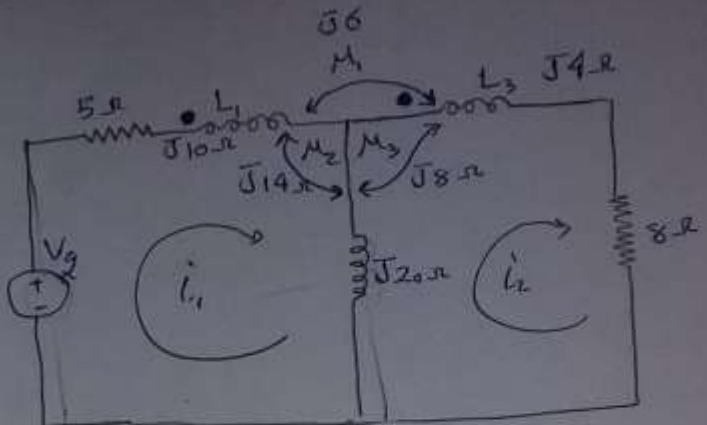
For Loop (2)

$$-88(i_2 - i_1) - L_2 \frac{di_2}{dt} - M \frac{di_1}{dt} - 200i_2 = 0$$

c)

حصافة هو المعلمات لـ لاديوس
عليها (Dot+) دلا (↔) دفه

(self Inductance)



داخل على (Dot+) فتحت على i_1 *

$$L_1 \rightarrow M_2 \frac{di_1}{dt}, L_3 \rightarrow M_3 \frac{di_1}{dt}$$

ذى يسبب ذى نفس (i1 - i2) *

$$L_1 \rightarrow M_2 \frac{d(i_1 - i_2)}{dt} (+ -), L_3 \rightarrow M_3 \frac{d(i_1 - i_2)}{dt} (+ -)$$

داخل i_2 *

$$L_1 \rightarrow M_1 \frac{di_2}{dt}, L_2 \rightarrow M_3 \frac{di_2}{dt}$$

For Loop (1)

$$V_2 - 5i_1 - L_1 \frac{di_1}{dt} - M_1 \frac{di_2}{dt} - M_2 \frac{d(i_1 - i_2)}{dt} - L_2 \frac{d(i_1 - i_2)}{dt}$$

$$-M_3 \frac{d(i_2 - i_1)}{dt} - M_2 \frac{di_1}{dt} = 0$$

For Loop (2)

$$-L_2 \frac{d(i_2 - i_1)}{dt} + M_2 \frac{di_1}{dt} + M_3 \frac{di_2}{dt} - L_3 \frac{di_2}{dt}$$

$$-M_1 \frac{di_1}{dt} - M_3 \frac{d(i_2 - i_1)}{dt} - 8i_2 = 0$$

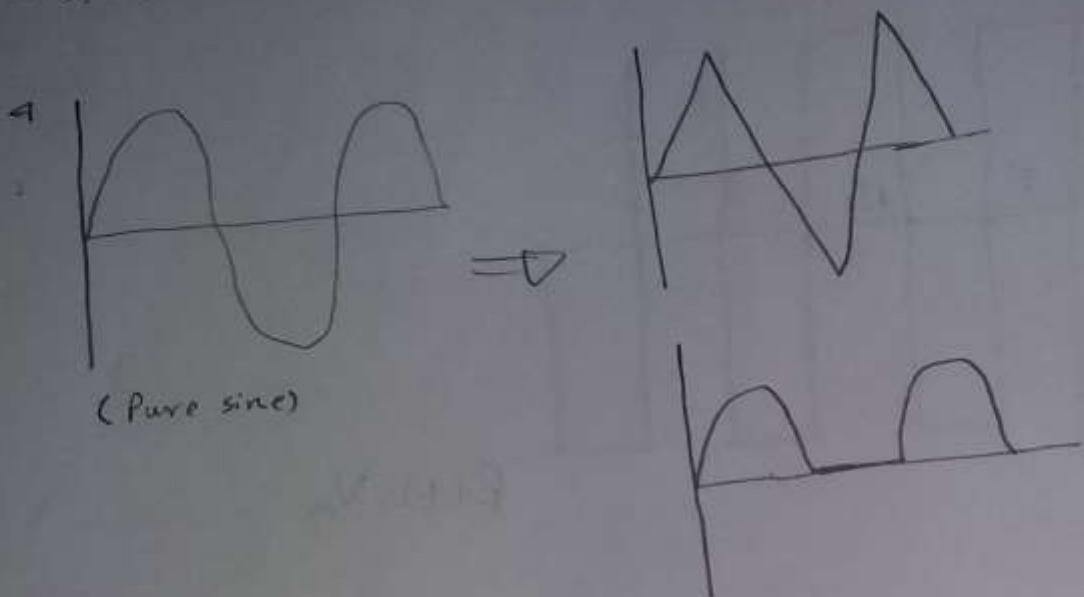
Ch:5

Fourier

Ch:5

Fourier series

* تؤثر على الموجة (AC) دعومه باسترجاع انتار (Pure sine) و دللي دسب ريجو دشوارب



سوف ندرس هنا مثلاً نوعان
أي صور لها في الموجة عددي مركب (non sinusoidal and periodic)
sine, cosine مجرب (Pure sine)

$$f(t) = a_0 + \sum_{n=1}^{\infty} a_n \cos(n\omega_0 t) + b_n \sin(n\omega_0 t)$$

Angular frequency

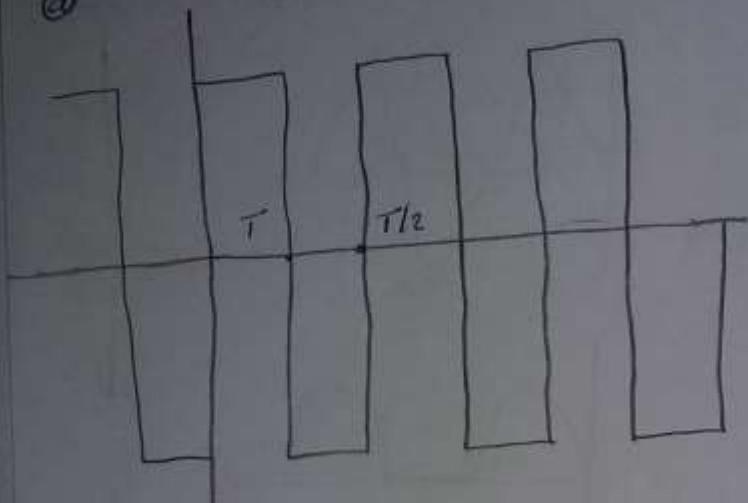
ω_0 → Frequency of a_0, a_n, b_n Fourier harmonic coefficients.
 $2\omega_0$ → Frequency of b_n

$$a_0 = \frac{1}{T} \int_{t_i}^{t_i+T} f(t) dt \quad (b_n = \frac{2}{T} \int_{t_i}^{t_i+T} f(t) \sin(n\omega_0 t) dt)$$

$$a_n = \frac{2}{T} \int_{t_i}^{t_i+T} f(t) \cos(n\omega_0 t) dt$$

1

②



$$f(t) = V_m$$

$$a_0 = 0, a_n = 0$$

$$b_n = \frac{4}{\pi T} \int_0^{T/2} f(t) \sin(n\omega_0 t) dt$$

$$= \frac{4}{T} \int_0^{T/2} V_m \sin(n\omega_0 t) dt$$

$$= \frac{4V_m}{T} \left[-\frac{\cos(n\omega_0 t)}{n\omega_0} \right]_0^{T/2}$$

$$= \frac{4V_m}{\pi T} \frac{2\pi}{f} \left[-\cos\left(n \frac{2\pi}{f} * \frac{T}{2}\right) + 1 \right]$$

$$b_n = \frac{2V_m}{n\pi} \frac{4V_m}{f}$$

مكامل حل نهود المتعدد

$$\omega_n = \frac{2\pi}{T}$$

$$P(t) = \sum_{n=1}^{\infty} b_n \sin(n\omega t)$$

$$= \sum_{n=1}^{\infty} \frac{4V_m}{n\pi} \sin(n\omega t)$$

$$\therefore \frac{4V_m}{\pi} \sin\omega t + \frac{4V_m}{3\pi} \sin 3\omega t + \dots$$

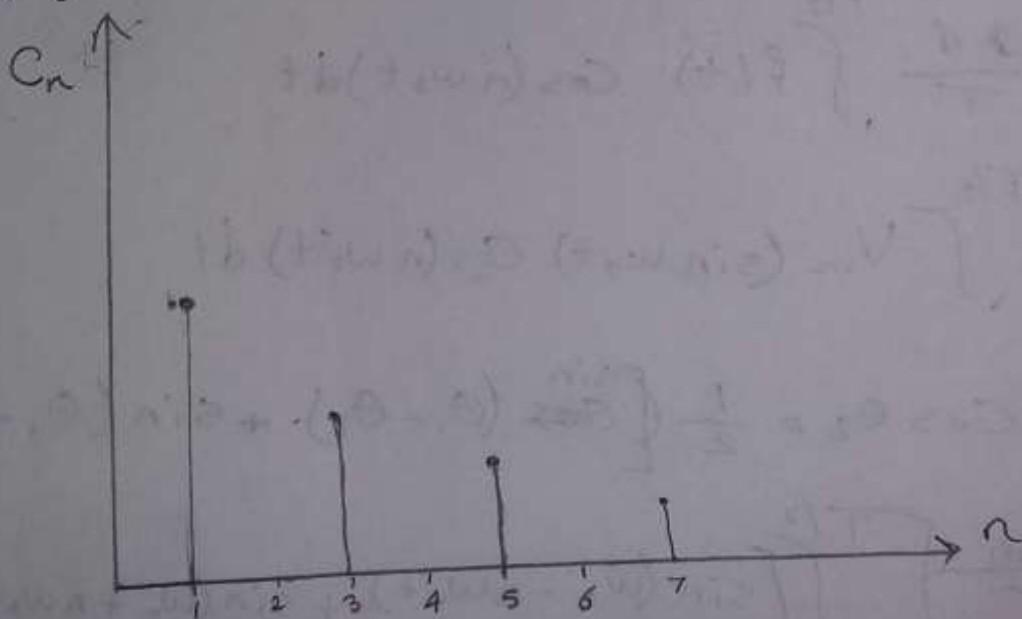
→ spectrum

$$C_n = \sqrt{a_n^2 + b_n^2} \quad (C_0 = a_0)$$

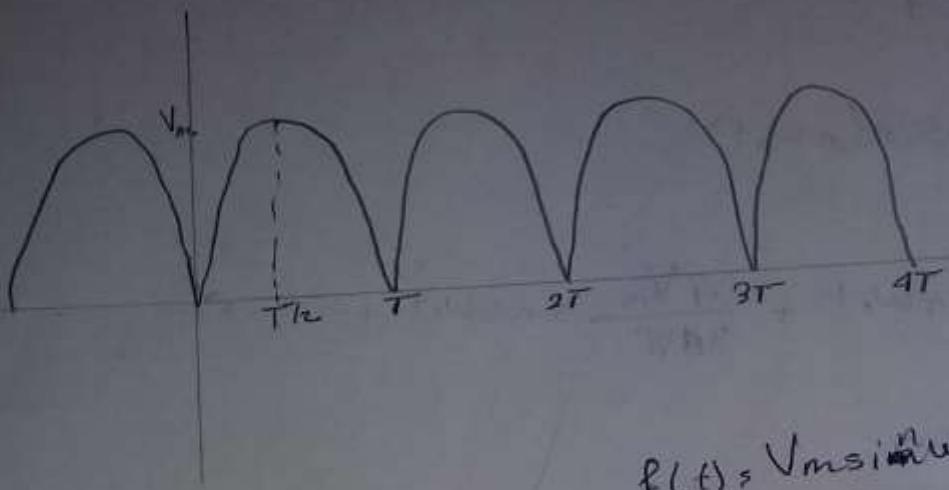
$$C_1 = \sqrt{a_1^2 + b_1^2} = \frac{4V_m}{\pi}$$

$$C_2 = \sqrt{a_2^2 + b_2^2} = 0$$

$$C_3 = \sqrt{a_3^2 + b_3^2} = \frac{4V_m}{3\pi}$$



b)



$$f(t) = V_m \sin(\omega_0 t)$$

even Function

$$a_0, a_n, b_n \quad [b_n = 0]$$

$$a_0 = \frac{2}{T} \int_{-T/2}^{T/2} f(t) dt = \frac{2}{T} \int_0^{T/2} V_m \sin(\omega_0 t) dt$$

$$= \frac{2V_m}{T} \left[-\frac{\cos(\omega_0 t)}{\omega_0} \right]_0^{T/2} = \frac{2V_m}{T}$$

$$a_n = \frac{2}{T} \int_{-T/2}^{T/2} f(t) \cos(n\omega_0 t) dt$$

$$= \frac{4}{T} \int_0^{T/2} V_m \sin(\omega_0 t) \cos(n\omega_0 t) dt$$

$$\sin \theta_1 \cos \theta_2 = \frac{1}{2} [\sin(\theta_1 - \theta_2) + \sin(\theta_1 + \theta_2)]$$

$$= \frac{4V_m}{T} \left[\int_0^{T/2} [\sin(\omega_0 - n\omega_0 t) + \sin(\omega_0 + n\omega_0 t)] dt \right]$$

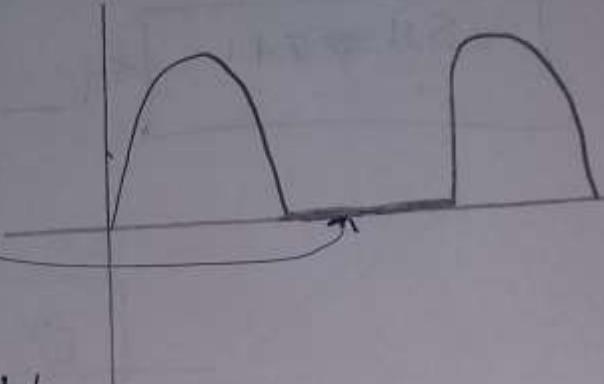
$$= \frac{2V_m}{T} \left[-\frac{\cos(\omega_0 - n\omega_0 t)}{\omega_0(1-n)} - \frac{\cos(\omega_0 + n\omega_0 t)}{\omega_0(1+n)} \right]_0^{T/2}$$

$$= \frac{2V_m}{T * \frac{2\pi}{T}} \left[\frac{-\cos((1-n)\frac{2\pi}{T}\frac{T}{2})}{1-n} - \frac{\cos((1+n)\frac{2\pi}{T}\frac{T}{2})}{1+n} + \frac{1}{1-n} + \frac{1}{1+n} \right]$$

$$= \frac{4V_m/\pi}{1-4n^2}$$

[3]

$$a_0 = \frac{1}{T} \int_0^{T/2} V_m \sin \omega_0 t dt + 0$$



$$a_n = \frac{1}{T} \int_0^{T/2} V_m \sin \omega_0 t \cos(n\omega_0 t) dt + 0$$

$$b_n = \frac{1}{T} \int_0^{T/2} [V_m \sin \omega_0 t - \sin(n\omega_0 t)] dt + 0$$

Ch:6

Operational amplifier

Ch.6

operational amplifier

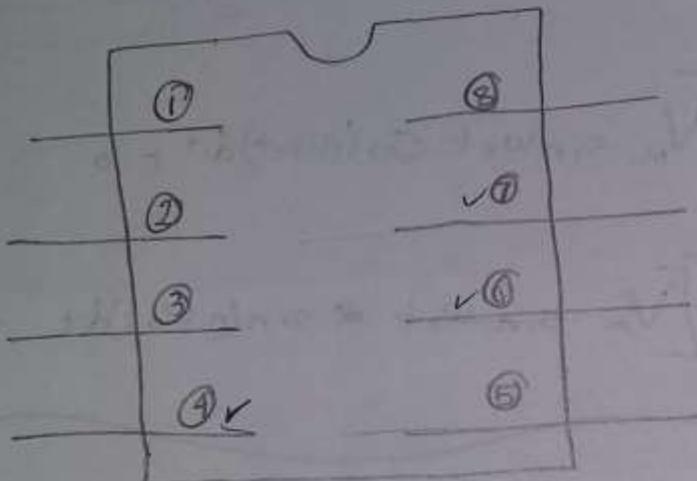
* عباره عن دوائر متکامله مستخدم بعلیس معینه مثل اینجا

* from analogue computer

دوائر متکامله دوائر بها مقادیر و مدلات و عکسها مرتبطة مع بعضها مستخدم بمحاسب.

741

* دیگر هر قاس از "A", "D", "V", "I"



② → inverting input

③ → non inverting input

④ → -ve supply

⑤ → +ve supply

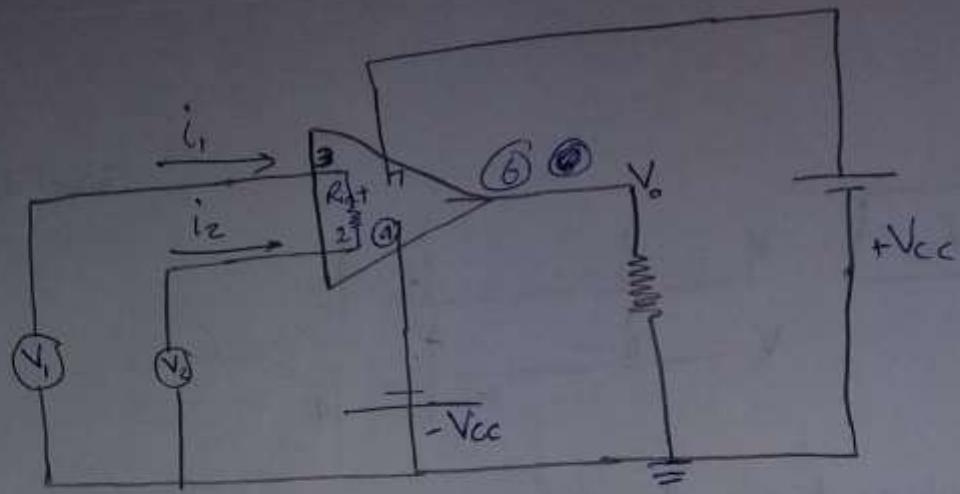
⑥ not connected

①, ⑦ → null offset

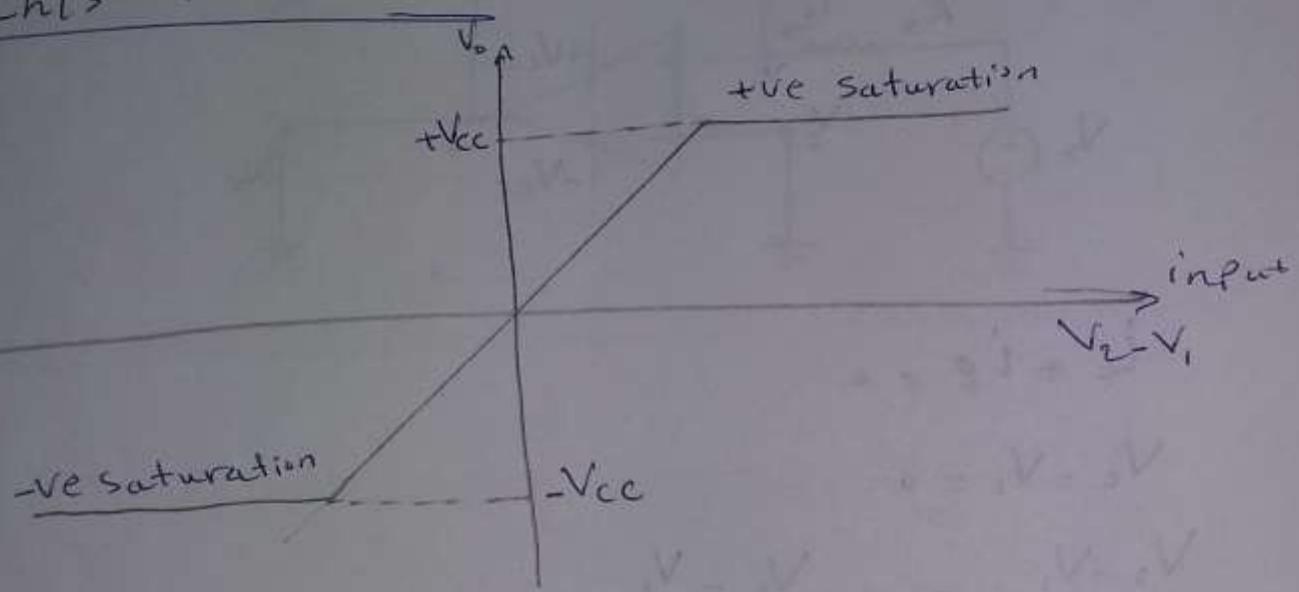
③ out put

لهمى موجة مستعاره حاگزير
offset





* chls of amp.



$$V_0 = A(V_2 - V_1)$$

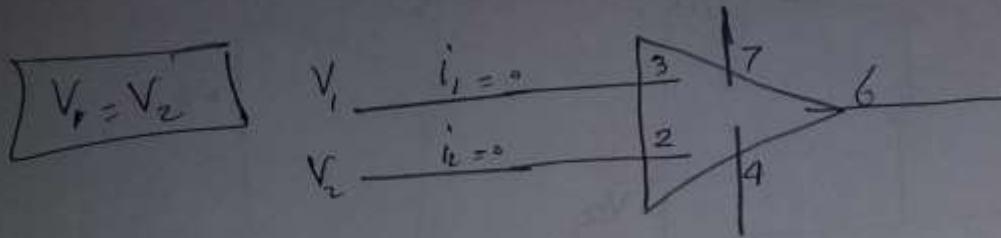
$A \rightarrow$ Gain

at ideal $\Rightarrow A \rightarrow$ very large $\approx \infty$

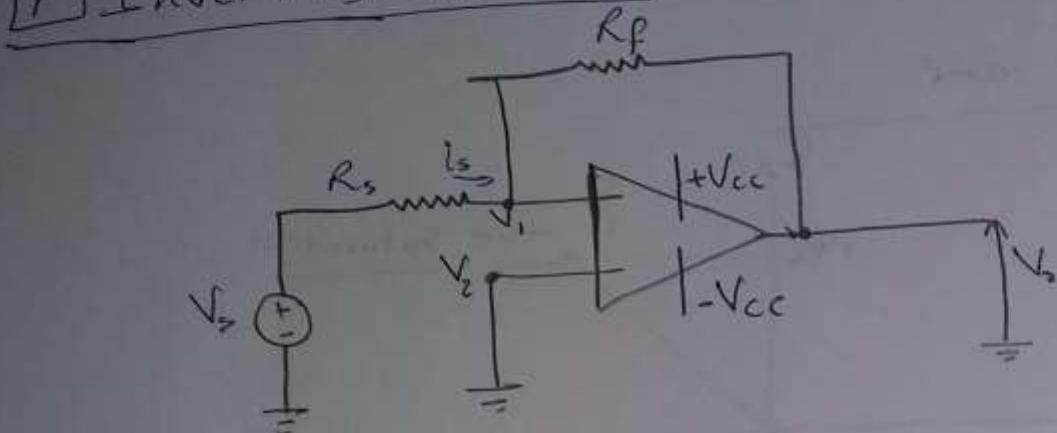
$$\therefore \frac{V_2 - V_1}{1} = \frac{V_0}{A \uparrow}$$

$\therefore V_2 - V_1 \approx 0$

$$\therefore \boxed{V_2 = V_1}$$



1 Inverting Amplifier



$$i_s + i_f = 0$$

$$V_2 = V_1 = 0$$

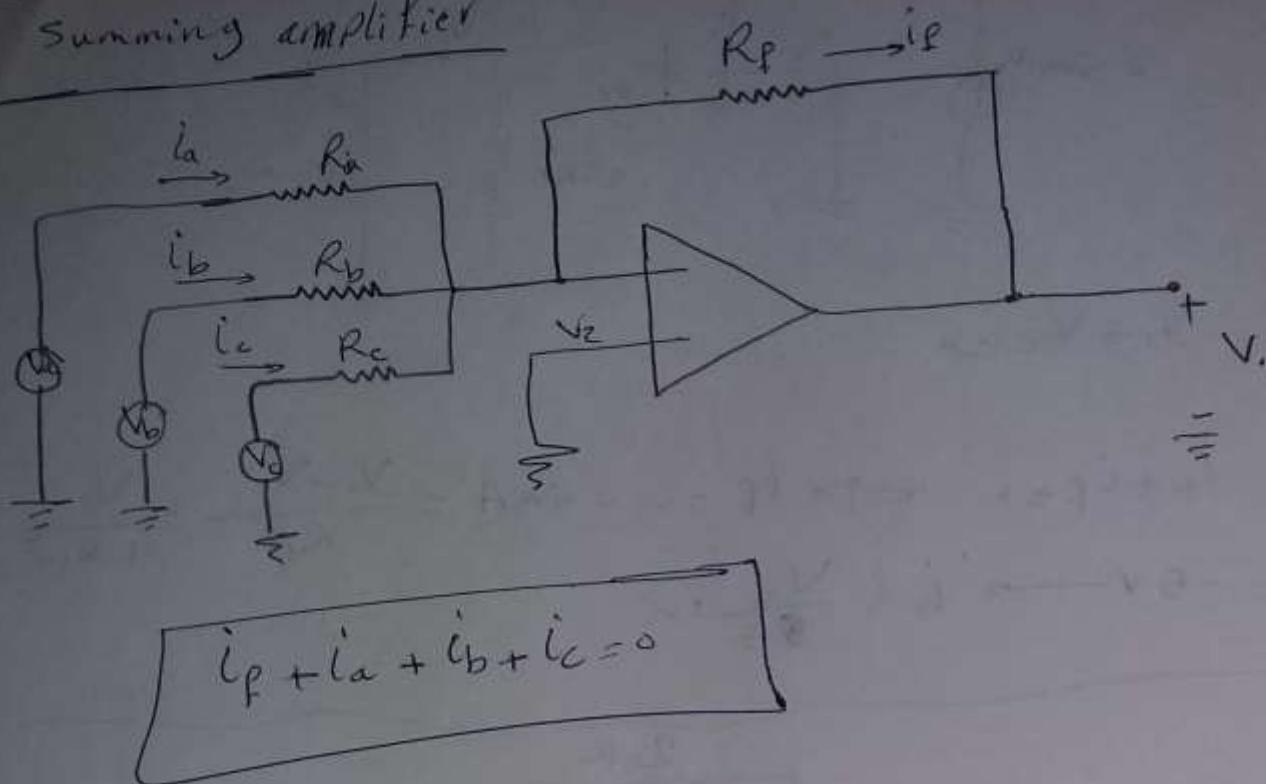
$$\frac{V_s - V_1}{R_s} \rightarrow + \frac{V_o - V_1}{R_f}$$

$$\frac{V_s}{R_s} = \frac{-V_o}{R_f}$$

$V_o = -\frac{R_f}{R_s} V_s$

↓ inverted

2

Summing amplifier

$$V_1 = V_2 = 0$$

$$\frac{V_o}{R_f} + \frac{V_a}{R_a} + \frac{V_b}{R_b} + \frac{V_c}{R_c} = 0$$

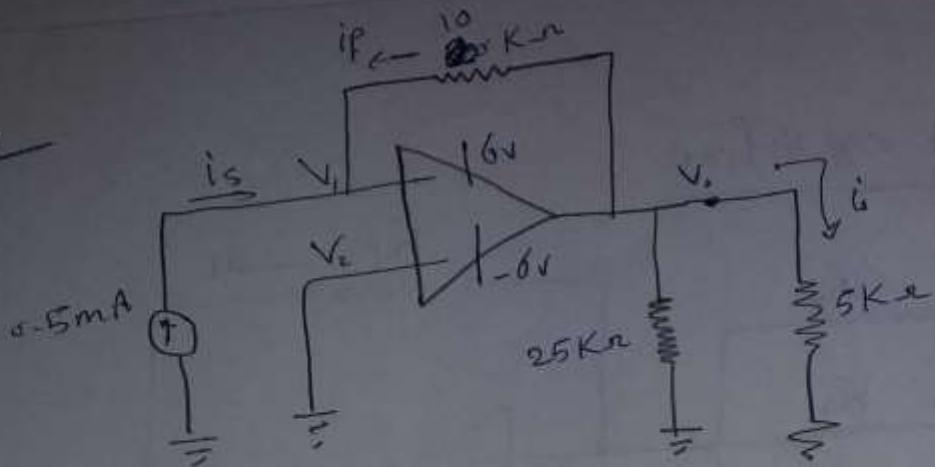
$$V_o = \left(-\frac{V_a}{R_a} - \frac{V_b}{R_b} - \frac{V_c}{R_c} \right) R_f$$

$$V_o = - \left(\frac{R_f}{R_a} V_a + \frac{R_f}{R_b} V_b + \frac{R_f}{R_c} V_c \right)$$

if $R_a = R_b = R_c = R_f$

$$V_o = - (V_a + V_b + V_c)$$

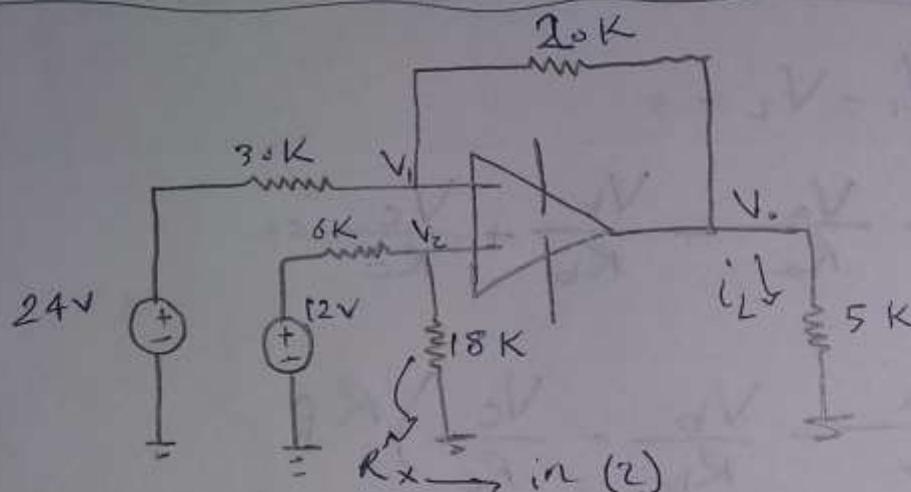
Find i_o



$$V_1 = V_2 = 0$$

$$i_s + i_F = 0 \Rightarrow i_F = -0.5\text{mA} = \frac{V_o - V_1}{R_F} = \frac{V_o}{10 \times 10^3}$$

$$V_o = -5 \text{ V} \rightarrow i_o = \frac{V_o}{5} = -1 \text{ mA}$$



$$V_1 = V_2 = 12 \times \frac{18}{18+6} = 9\text{V}$$

$$i_s + i_F = 0$$

$$\frac{24 - 9}{3 \times 10^3} \rightarrow \frac{V_o - 9}{20 \times 10^3} = -1 \text{ mA}$$

$$V_o = -1 \text{ V}$$

$$i_L = \frac{V_o}{5 \times 10^3} = -0.2 \text{ mA}$$

* Find value of R_x so that (op. amp) not saturated

$$\frac{24 - V_1}{30 \times 10^3} + \frac{V_o - V_1}{20 \times 10^3} = 0$$

$$\frac{24}{30} - \frac{V_1}{30} + \frac{V_o}{20} - \frac{V_1}{20} = 0$$

$$V_1 \left(\frac{1}{30} + \frac{1}{20} \right) + \frac{24}{30} + \frac{V_o}{20}$$

$$V_o = 5V \Rightarrow V_1 = \frac{\frac{24}{30} - \frac{1}{20}}{\frac{1}{30} + \frac{1}{20}} = 12 \frac{R_x}{R_x + 6 \times 10^3}$$

$$V_o = 5V \Rightarrow V_1 = 0$$

$$\therefore R_x < \dots$$